

RISK OF ESTIMATORS FOR POINT SYMMETRY AND  
DOUBLE SYMMETRY MODELS FOR SQUARE  
CONTINGENCY TABLES

Kouji Tahata<sup>1</sup> §, Takahiro Inoue<sup>2</sup>, Sadao Tomizawa<sup>3</sup>

<sup>1,2,3</sup>Department of Information Sciences

Faculty of Science and Technology

Tokyo University of Science

2641, Yamazaki, Noda City, Chiba, 278-8510, JAPAN

<sup>1</sup>e-mail: kouji\_tahata@is.noda.tus.ac.jp

<sup>3</sup>e-mail: tomizawa@is.noda.tus.ac.jp

**Abstract:** For contingency tables, Bishop, Fienberg and Holland [1] gave the expected mean squared error (risk) of the maximum likelihood estimators (MLEs) of cell probabilities for the independence model, and Tahata, Miyamoto, Sasajima, and Tomizawa [4] gave the conditional risks of the MLEs for the symmetry and conditional symmetry models.

The present paper gives the risks of those for the point symmetry model and the double symmetry model for square contingency tables. The paper also compares the risks for these models.

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**Key Words:** double symmetry, mean squared error, point symmetry, risk, square tables

## 1. Introduction

For an  $r \times r$  square contingency table with the same row and column classifications, let  $p_{ij}$  denote the probability that an observation will fall in the  $i$ -th

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§Correspondence author

row and  $j$ -th column of the table ( $i = 1, \dots, r; j = 1, \dots, r$ ). The symmetry (S) model is defined by

$$p_{ij} = p_{ji} \quad (i = 1, \dots, r; j = 1, \dots, r);$$

see Bowker [2], and Bishop, Fienberg and Holland [1, p. 282]. This indicates the symmetry of cell probabilities with respect to the main diagonal of the  $r \times r$  table. Wall and Lienert [6] defined the point symmetry (PS) model by

$$p_{ij} = p_{i^*j^*} \quad (i = 1, \dots, r; j = 1, \dots, r),$$

where  $i^* = r + 1 - i$  and  $j^* = r + 1 - j$ . This indicates the symmetry of cell probabilities with respect to the center point of the  $r \times r$  table. Tomizawa [5] considered the double symmetry (DS) model by

$$p_{ij} = p_{ji} = p_{i^*j^*} = p_{j^*i^*} \quad (i = 1, \dots, r; j = 1, \dots, r).$$

This model indicates that both of S and PS hold.

Let  $x_{ij}$  be the observed frequency in cell  $(i, j)$  of the table with  $N = \sum \sum x_{ij}$ . Assume that  $\{x_{ij}\}$  have a multinomial distribution. Let  $T_{ij}^{(M)}$  be the maximum likelihood estimator (MLE) of the cell probability  $p_{ij}$  under model  $M$ .

The expected mean squared error (risk) for the MLEs of  $\{p_{ij}\}$  for model  $M$  is

$$\begin{aligned} R_M &= \sum_{i=1}^r \sum_{j=1}^r E \left[ \left( T_{ij}^{(M)} - p_{ij} \right)^2 \right] \\ &= \sum_{i=1}^r \sum_{j=1}^r \left( \text{Var} \left( T_{ij}^{(M)} \right) + \text{Bias} \left( T_{ij}^{(M)} \right) \right), \end{aligned}$$

where

$$\begin{aligned} \text{Var} \left( T_{ij}^{(M)} \right) &= E \left[ \left( T_{ij}^{(M)} - E \left( T_{ij}^{(M)} \right) \right)^2 \right], \\ \text{Bias} \left( T_{ij}^{(M)} \right) &= \left[ E \left( T_{ij}^{(M)} \right) - p_{ij} \right]^2. \end{aligned}$$

Bishop et al [1, p. 313] gave the risk of MLEs of cell probabilities for the independence model. Tahata, Miyamoto, Sasajima and Tomizawa [4] gave the conditional risks of MLEs of cell probabilities for the S model, the saturated (SA) model and McCullagh's [3] conditional symmetry model on condition that an observation falls in one of the off-diagonal cells of the square contingency table.

The purpose of the present paper is to give the risks of MLEs of cell probabilities for the PS model and the DS model for square contingency tables.

## 2. Risks of MLEs for Models

Consider the  $r \times r$  contingency table. The MLEs of cell probabilities  $\{p_{ij}\}$  under the SA model are given by

$$T_{ij}^{(SA)} = \frac{x_{ij}}{N} \quad (i = 1, \dots, r; j = 1, \dots, r).$$

Thus the risk for the SA model is

$$R_{SA} = \frac{1}{N} \left( 1 - \sum_{i=1}^r \sum_{j=1}^r p_{ij}^2 \right).$$

Also, the MLEs for  $\{p_{ij}\}$  under the S model are given by

$$T_{ij}^{(S)} = \frac{x_{ij} + x_{ji}}{2N} \quad (i = 1, \dots, r; j = 1, \dots, r).$$

Thus the risk for the S model is

$$\begin{aligned} R_S &= \sum_{i \neq j} \sum_{j=1}^r \frac{1}{4} \left[ \frac{1}{N} \left\{ (p_{ij} + p_{ji}) - (p_{ij} + p_{ji})^2 \right\} + (p_{ji} - p_{ij})^2 \right] \\ &\quad + \sum_{i=1}^r \frac{1}{N} p_{ii} (1 - p_{ii}). \end{aligned}$$

### 2.1. Risk for Point Symmetry Model

Denote  $\frac{r+1}{2}$  by  $c$ . The MLEs of cell probabilities  $\{p_{ij}\}$  under the PS model are given by

$$T_{ij}^{(PS)} = \begin{cases} \frac{x_{ij} + x_{i^*j^*}}{2N} & (i, j) \neq (c, c), \\ \frac{x_{cc}}{N} & (i, j) = (c, c), \end{cases}$$

where cell  $(c, c)$  does not exist when  $r$  is even. We see

$$E \left( T_{ij}^{(PS)} \right) = \begin{cases} \frac{p_{ij} + p_{i^*j^*}}{2} & (i, j) \neq (c, c), \\ p_{cc} & (i, j) = (c, c). \end{cases}$$

When the PS model holds,  $T_{ij}^{(PS)}$  is an unbiased estimator of  $p_{ij}$ . Also, by considering

$$\text{Var} \left( T_{ij}^{(PS)} \right) = \frac{1}{4N^2} \left( \text{Var} (x_{ij}) + \text{Var} (x_{i^*j^*}) + 2\text{Cov} (x_{ij}, x_{i^*j^*}) \right)$$

for  $(i, j) \neq (c, c)$ , we find the variance term as

$$\text{Var} \left( T_{ij}^{(PS)} \right) = \begin{cases} \frac{(p_{ij} + p_{i^*j^*}) - (p_{ij} + p_{i^*j^*})^2}{4N} & (i, j) \neq (c, c), \\ \frac{p_{cc}(1 - p_{cc})}{N} & (i, j) = (c, c). \end{cases}$$

Also the bias term is

$$\text{Bias} \left( T_{ij}^{(PS)} \right) = \begin{cases} \frac{(p_{i^*j^*} - p_{ij})^2}{4} & (i, j) \neq (c, c), \\ 0 & (i, j) = (c, c). \end{cases}$$

Thus we can obtain the risk for the PS model as

$$R_{PS} = \begin{cases} \sum_{(i,j) \neq (c,c)} \sum \frac{1}{4} \left[ \frac{1}{N} \left\{ (p_{ij} + p_{i^*j^*}) - (p_{ij} + p_{i^*j^*})^2 \right\} + (p_{i^*j^*} - p_{ij})^2 \right] \\ + \frac{1}{N} p_{cc}(1 - p_{cc}) & (\text{when } r \text{ is odd}), \\ \sum_{i=1}^r \sum_{j=1}^r \frac{1}{4} \left[ \frac{1}{N} \left\{ (p_{ij} + p_{i^*j^*}) - (p_{ij} + p_{i^*j^*})^2 \right\} + (p_{i^*j^*} - p_{ij})^2 \right] & (\text{when } r \text{ is even}). \end{cases}$$

## 2.2. Risk for Double Symmetry Model

Define the sets of cells as follows:

$$\begin{aligned} D_1 &= \{(i, j) \mid i = 1, \dots, r; j = 1, \dots, r; i \neq j; j \neq i^*\}, \\ D_2 &= \{(i, j) \mid i = 1, \dots, r; i = j; (i, j) \neq (c, c)\}, \\ D_3 &= \{(i, j) \mid i = 1, \dots, r; j = i^*; (i, j) \neq (c, c)\}, \\ D_4 &= \{(i, j) \mid i = j = c\}. \end{aligned}$$

Note that  $D_4$  is defined only when  $r$  is odd. The MLEs of  $\{p_{ij}\}$  under the DS model are given by

$$T_{ij}^{(DS)} = \begin{cases} \frac{x_{ij} + x_{ji} + x_{i^*j^*} + x_{j^*i^*}}{4N} & (i, j) \in D_1, \\ \frac{x_{ii} + x_{i^*i^*}}{2N} & (i, j) \in D_2, \\ \frac{x_{ii^*} + x_{i^*i}}{2N} & (i, j) \in D_3, \\ \frac{x_{cc}}{N} & (i, j) \in D_4. \end{cases}$$

We see

$$E\left(T_{ij}^{(DS)}\right) = \begin{cases} \frac{p_{ij} + p_{ji} + p_{i^*j^*} + p_{j^*i^*}}{4} & (i, j) \in D_1, \\ \frac{p_{ii} + p_{i^*i^*}}{2} & (i, j) \in D_2, \\ \frac{p_{ii^*} + p_{i^*i}}{2} & (i, j) \in D_3, \\ p_{cc} & (i, j) \in D_4. \end{cases}$$

When the DS model holds,  $T_{ij}^{(DS)}$  is an unbiased estimator of  $p_{ij}$ .

The variance term is expressed by

$$\text{Var}\left(T_{ij}^{(DS)}\right) = \begin{cases} \frac{(p_{ij} + p_{ji} + p_{i^*j^*} + p_{j^*i^*}) - (p_{ij} + p_{ji} + p_{i^*j^*} + p_{j^*i^*})^2}{16N} & (i, j) \in D_1, \\ \frac{(p_{ii} + p_{i^*i^*}) - (p_{ii} + p_{i^*i^*})^2}{4N} & (i, j) \in D_2, \\ \frac{(p_{ii^*} + p_{i^*i}) - (p_{ii^*} + p_{i^*i})^2}{4N} & (i, j) \in D_3, \\ \frac{p_{cc}(1 - p_{cc})}{N} & (i, j) \in D_4. \end{cases}$$

The bias term is

$$\text{Bias}\left(T_{ij}^{(DS)}\right) = \begin{cases} \frac{(p_{ji} + p_{i^*j^*} + p_{j^*i^*} - 3p_{ij})^2}{16} & (i, j) \in D_1, \\ \frac{(p_{i^*i^*} - p_{ii})^2}{4} & (i, j) \in D_2, \\ \frac{(p_{i^*i} - p_{ii^*})^2}{4} & (i, j) \in D_3, \\ 0 & (i, j) \in D_4. \end{cases}$$

Therefore the risk for the DS model is given as follows:

When  $r$  is odd,

$$\begin{aligned} R_{DS} &= \sum_{(i,j) \in D_1} \sum \frac{1}{16} \left[ \frac{1}{N} (A_{ij} - A_{ij}^2) + (A_{ij} - 4p_{ij})^2 \right] \\ &\quad + \sum_{(i,j) \in D_2} \sum \frac{1}{4} \left[ \frac{1}{N} (B_{ij} - B_{ij}^2) + (B_{ij} - 2p_{ii})^2 \right] \\ &\quad + \sum_{(i,j) \in D_3} \sum \frac{1}{4} \left[ \frac{1}{N} (C_{ij} - C_{ij}^2) + (C_{ij} - 2p_{ii^*})^2 \right] \end{aligned}$$

$$+\frac{1}{N}p_{cc}(1-p_{cc}),$$

and when  $r$  is even,

$$\begin{aligned} R_{DS} &= \sum_{(i,j) \in D_1} \sum \frac{1}{16} \left[ \frac{1}{N} (A_{ij} - A_{ij}^2) + (A_{ij} - 4p_{ij})^2 \right] \\ &\quad + \sum_{(i,j) \in D_2} \sum \frac{1}{4} \left[ \frac{1}{N} (B_{ij} - B_{ij}^2) + (B_{ij} - 2p_{ii})^2 \right] \\ &\quad + \sum_{(i,j) \in D_3} \sum \frac{1}{4} \left[ \frac{1}{N} (C_{ij} - C_{ij}^2) + (C_{ij} - 2p_{ii^*})^2 \right], \end{aligned}$$

where  $A_{ij} = p_{ij} + p_{ji} + p_{i^*j^*} + p_{j^*i^*}$ ,  $B_{ij} = p_{ii} + p_{i^*i^*}$ , and  $C_{ij} = p_{ii^*} + p_{i^*i}$ .

### 3. Comparisons between Risks

We can obtain the following theorems from comparing the risks for the SA, S, PS, and DS models.

**Theorem 1.** *When the PS model holds,*

$$R_{SA} - R_{PS} = \begin{cases} \frac{1}{2N} \sum_{(i,j) \neq (c,c)} p_{ij} & (\text{when } r \text{ is odd}), \\ \frac{1}{2N} & (\text{when } r \text{ is even}). \end{cases}$$

**Theorem 2.** *When the DS model holds,*

$$R_{SA} - R_{DS} = \frac{3}{4N} \sum_{(i,j) \in D_1} p_{ij} + \frac{1}{2N} \sum_{(i,j) \in D_2} p_{ii} + \frac{1}{2N} \sum_{(i,j) \in D_3} p_{ii^*}.$$

**Theorem 3.** *When the DS model holds,*

$$R_S - R_{DS} = \frac{1}{4N} \sum_{(i,j) \in D_1} p_{ij} + \frac{1}{2N} \sum_{(i,j) \in D_2} p_{ii}.$$

**Theorem 4.** *When the DS model holds,*

$$R_{PS} - R_{DS} = \frac{1}{4N} \sum_{(i,j) \in D_1} p_{ij}.$$

We see that

(1) from Theorem 1, when the PS model holds,  $R_{PS} < R_{SA}$ ,

- (2) from Theorem 2, when the DS model holds,  $R_{DS} < R_{SA}$ ,
- (3) from Theorem 3, when the DS model holds,  $R_{DS} < R_S$ ,
- (4) from Theorem 4, when the DS model holds,  $R_{DS} < R_{PS}$ .

Thus we see that the overall variability for the estimators based on the PS model is smaller than that based on the SA model when the PS model is correct. Also the overall variability based on the DS model is smaller than that based on the SA, S, and PS models when DS model is correct.

#### 4. Concluding Remark

By comparing the risks between the models in terms of Theorems 1, 2, 3, and 4, we find that when the simpler model is correct, the overall variability for the estimators based on the simpler model is smaller than the estimator based on the more complicated model.

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