

ON QUASI- (E, F) -CONVEX FUNCTIONS AND
QUASI- (E, F) -CONVEX PROGRAMMING

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Abstract: In this paper, a new class of generalized convex functions, called quasi- (E, F) -convex functions, is introduced. Some important properties of it are developed. Further, we introduce quasi- (E, F) -convex programmings and investigate their optimal properties.

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1. Introduction

Convexity and generalized convexity play a significant role in optimization theory. The research on convexity and generalized convexity is popular for many years. For example, Finetti [1] first studied quasi-convexity in 1949. Mangassarian [2] brought forward pseudo-convexity in 1965. Youness [3] introduced E -convex sets and E -convex functions, discussed some of their basic properties and established some optimal results of E -convex programming, which is based on the effect of an operator E on the sets in 1999. By extending E -convexity, Jian [4] introduced (E, F) -convexity, which is based on the effect of two point-to-set maps E and F . Based on [4], Jian, Hu, Tang and Zheng [6] further introduced semi- (E, F) -convex functions and semi- (E, F) -convex programming. In addition, there are some new achievements in recent years (see [7]-[9]).

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In this paper, motivated by the idea in [4], we first introduce a new class of generalized convex function, i.e., quasi-(E, F)-convex functions, and discuss some important properties. And then we introduce quasi-(E, F)-convex programmings and investigate their optimal properties. For convenience, we first restate some definitions in [4] as follows.

Definition 1.1. A set $M \subseteq R^n$ is said to be an (E,F)-convex set, if there exist two point-to-set maps $E, F : R^n \rightarrow 2^{R^n}$ such that

$$\lambda E(x) + (1 - \lambda)F(y) \subseteq M, \forall x, y \in M, \forall \lambda \in [0, 1].$$

Definition 1.2. A map $f : R^n \rightarrow R$ is said to be an (E,F)-convex function on a set $M \subseteq R^n$ if there exist two point-to-set maps $E, F : R^n \rightarrow 2^{R^n}$ such that M is an (E,F)-convex set and

$$f(\lambda \bar{x} + (1 - \lambda)\bar{y}) \leq \lambda f(\bar{x}) + (1 - \lambda)f(\bar{y}),$$

$$\forall \bar{x} \in E(x), \forall \bar{y} \in F(y), \forall x, y \in M, \forall \lambda \in [0, 1].$$

Definition 1.3. A point-to-set map $E: R^n \rightarrow 2^{R^n}$ is said to be a preservative map of set $M \subseteq R^n$ if $E(M) \subseteq M$, i.e., $E(x) \subseteq M, \forall x \in M$.

Definition 1.4. Given $f: R^n \rightarrow R, M \subseteq R^n$. A map $E: R^n \rightarrow 2^{R^n}$ is said to be a contractive map of function f on M , if

$$\sup f(E(x)) \leq f(x), \forall x \in M.$$

A map $E : R^n \rightarrow 2^{R^n}$ is said to be an expanding map of f on M if

$$\inf f(E(x)) \geq f(x), \forall x \in M.$$

Theorem 1.5. [4] *A set $M \subseteq R^n$ is a convex set if and only if M is an (E,F)-convex set for all preservative maps E and F of set M .*

2. Quasi-(E, F)-Convex Functions and their Properties

In this section, we present the definition of quasi-(E, F)-convex functions and discuss some main properties of quasi-(E, F)-convex functions.

Definition 2.1. A map $f : R^n \rightarrow R$ is said to be a quasi-(E,F)-convex function on a set $M \subseteq R^n$ if the two point-to-set maps $E, F : R^n \rightarrow 2^{R^n}$ ensure that M is an (E,F)-convex set and

$$f(\lambda\bar{x} + (1 - \lambda)\bar{y}) \leq \max\{f(\bar{x}), f(\bar{y})\},$$

$$\forall \bar{x} \in E(x), \forall \bar{y} \in F(y), \forall x, y \in M, \forall \lambda \in [0, 1].$$

Furthermore, if the inequality above is strict for $\bar{x} \neq \bar{y}$ and $\lambda \in (0, 1)$, then f is called strictly quasi-(E,F)-convex on M .

The following proposition holds true clearly from the above definition.

Proposition 2.2. *Each (E,F)-convex function is also a quasi-(E,F)-convex function.*

Theorem 2.3. *Let $M \subseteq R^n$ be a convex set. Then a map $f : R^n \rightarrow R$ is a quasi-convex function on M if and only if f is a quasi-(E,F)-convex function on M for any preservative maps E, F of set M .*

Proof. Assume that f is quasi-convex on M , and $E, F : R^n \rightarrow 2^{R^n}$. Since E, F are preservative maps of M , we have $E(M) \subseteq M, F(M) \subseteq M$. One knows that M is (E, F) -convex set from Theorem 1.5. So we have

$$f(\lambda\bar{x} + (1 - \lambda)\bar{y}) \leq \max\{f(\bar{x}), f(\bar{y})\}, \forall \bar{x} \in E(x), \forall \bar{y} \in F(y), \forall x, y \in M,$$

therefore f is a quasi-(E, F)-convex function on M .

Conversely, if f is quasi-(E, F)-convex for any preservative maps E, F of set M , then, take maps $E = F$ as the identity map, one can know that f is quasi-convex on M . The proof is complete. □

Theorem 2.4. *Let functions $f, g: R^n \rightarrow R$ be quasi-(E,F)-convex on $M \subseteq R^n$, then for any constants $\alpha, \beta \geq 0$, the function $(\alpha f + \beta g)$ is quasi-(E,F)-convex on M .*

The proof is obvious and omitted.

Theorem 2.5. *Suppose that $M \subseteq R^n$ is an (E, F)-convex set and $\{f_i\}_{i \in I}$ is a family of numerical functions which are quasi-(E, F)-convex and bounded on M . Then the function $f(x) = \sup_{i \in I} f_i(x)$ is quasi-(E, F)-convex on M .*

Proof. For any $x, y \in M, \forall \lambda \in [0, 1]$ and $\forall \bar{x} \in E(x), \forall \bar{y} \in F(y)$, by using the quasi-(E, F)-convexity of f_i on M , one has

$$f(\lambda\bar{x} + (1 - \lambda)\bar{y}) = \sup_{i \in I} f_i(\lambda\bar{x} + (1 - \lambda)\bar{y}) \leq \sup_{i \in I} \{\max\{f_i(\bar{x}), f_i(\bar{y})\}\}. \tag{1}$$

In what follows, we will prove the following inequality holds true

$$\sup_{i \in I} \{\max\{f_i(\bar{x}), f_i(\bar{y})\}\} \leq \max\{\sup_{i \in I} f_i(\bar{x}), \sup_{i \in I} f_i(\bar{y})\}.$$

Noting that

$$f_i(\bar{x}) \leq \sup_{i \in I} f_i(\bar{x}), f_i(\bar{y}) \leq \sup_{i \in I} f_i(\bar{y}), \forall i \in I,$$

we have

$$\max\{f_i(\bar{x}), f_i(\bar{y})\} \leq \max\{\sup_{i \in I} f_i(\bar{x}), \sup_{i \in I} f_i(\bar{y})\},$$

further, we obtain

$$\sup_{i \in I} \{\max\{f_i(\bar{x}), f_i(\bar{y})\}\} \leq \max\{\sup_{i \in I} f_i(\bar{x}), \sup_{i \in I} f_i(\bar{y})\},$$

which together with (1) gives

$$f(\lambda\bar{x} + (1 - \lambda)\bar{y}) \leq \max\{\sup_{i \in I} f_i(\bar{x}), \sup_{i \in I} f_i(\bar{y})\} = \max\{f(\bar{x}), f(\bar{y})\}.$$

It indicates that $f(x) = \sup_{i \in I} f_i(x)$ is quasi- (E, F) -convex on M . □

Theorem 2.6. *Let function $f : R^n \rightarrow R$ be quasi- (E, F) -convex on an (E, F) -convex set $M \subseteq R^n$. If E and F are contractive maps of f on M , then, for any $\alpha \in R$, the level set $S_\alpha \triangleq \{x \in M : f(x) \leq \alpha\}$ is an (E, F) -convex set.*

Proof. For any $x, y \in S_\alpha$, we have

$$x \in M, y \in M, f(x) \leq \alpha, f(y) \leq \alpha. \tag{2}$$

Noting that M is an (E, F) -convex set, we have $\lambda\bar{x} + (1 - \lambda)\bar{y} \in M$ for any $\bar{x} \in E(x), \bar{y} \in E(y)$ and any $\lambda \in [0, 1]$.

Since E, F are contractive maps, we have

$$f(\bar{x}) \leq f(x) \leq \alpha, f(\bar{y}) \leq f(y) \leq \alpha. \tag{3}$$

By using the quasi- (E, F) -convexity of f and (3), one knows

$$f(\lambda\bar{x} + (1 - \lambda)\bar{y}) \leq \max\{f(\bar{x}), f(\bar{y})\} \leq \alpha, \tag{4}$$

Hence, $\lambda\bar{x} + (1 - \lambda)\bar{y} \in S_\alpha$, i.e., S_α is an (E, F) -convex set. □

Theorem 2.7. *Let $M \subseteq R^n$ be an (E, F) -convex set. Suppose that level set $S_\alpha = \{x \in M : f(x) \leq \alpha\}$ for any $\alpha \in R$ is an (E, F) -convex set. If the maps E, F are expanding maps of f on M , then f is quasi- (E, F) -convex on M .*

Proof. For any $x, y \in M, \forall \bar{x} \in E(x), \bar{y} \in F(y)$, let $\alpha = \max\{f(\bar{x}), f(\bar{y})\}$. Since E, F are expanding maps, we have

$$f(x) \leq f(\bar{x}) \leq \alpha, \quad f(y) \leq f(\bar{y}) \leq \alpha.$$

So $x, y \in S_\alpha$. Further, for any $\lambda \in (0, 1)$, we have $\lambda E(x) + (1 - \lambda)F(y) \subseteq S_\alpha$ due to S_α is an (E, F) -convex set. Hence,

$$f(\lambda \bar{x} + (1 - \lambda)\bar{y}) \leq \alpha = \max\{f(\bar{x}), f(\bar{y})\}.$$

It indicates that f is quasi- (E, F) -convex on M . □

3. Quasi- (E, F) -Convex Programming

In this section, some important properties of quasi- (E, F) -convex programmings are discussed. Consider the following nonlinear programming problem

$$(NP) \quad \min \{f(x) : x \in M\}.$$

where $f : R^n \rightarrow R$ is continuously differentiable and $M \subseteq R^n$.

Definition 3.1. The problem (NP) is said to be a quasi- (E, F) -convex programming if the feasible set M is an (E, F) -convex set and the objective function f is quasi- (E, F) -convex on M .

Furthermore, if f is strictly quasi- (E, F) -convex on M , then problem (NP) is called a strictly quasi- (E, F) -convex programming.

Another programming problem connected with (NP) is as follows

$$(NP_{EF}) \quad \begin{array}{ll} \min & f(x) \\ \text{s.t.} & x \in E(M) \cap F(M). \end{array}$$

Denote

$$\begin{aligned} \Omega &= \{x \in R^n : x \text{ is a global optimal solution of (NP)}\}, \\ \Omega_{EF} &= \{x \in R^n : x \text{ is a global optimal solution of (NP}_{EF})\}. \end{aligned}$$

Theorem 3.2. Assume that problem (NP) is a quasi- (E, F) -convex programming. If E and F are preservative maps of Ω , then Ω is an (E, F) -convex set.

Proof. $\forall x, y \in \Omega$ and $\forall \lambda \in [0, 1]$, we have $x, y \in M$, further, $\lambda E(x) + (1 - \lambda)F(y) \subseteq M$. Denote $f^* \triangleq f(x) = f(y)$.

In what follows, we will prove $\lambda E(x) + (1 - \lambda)F(y) \subseteq \Omega$. It is sufficient to prove $\lambda \bar{x} + (1 - \lambda)\bar{y} \in \Omega$, $\forall \bar{x} \in E(x)$, $\forall \bar{y} \in E(y)$. Noting that E and F are preservative maps of Ω , we have $E(x) \subseteq \Omega$, $F(y) \subseteq \Omega$, so $f(\bar{x}) = f(\bar{y}) = f^*$.

Since f is quasi- (E, F) -convex on M , we have

$$f(\lambda \bar{x} + (1 - \lambda)\bar{y}) \leq \max\{f(\bar{x}), f(\bar{y})\} = f^*, \forall \bar{x} \in E(x), \forall \bar{y} \in F(y).$$

Therefore, $\lambda \bar{x} + (1 - \lambda)\bar{y}$ is a global solution, i.e., $\lambda \bar{x} + (1 - \lambda)\bar{y} \in \Omega$. □

Theorem 3.3. *Suppose that problem (NP_{EF}) is a quasi- (E, F) -convex programming and $E(M) \cap F(M)$ is a convex set, then*

- (1) *The solution set Ω_{EF} is a convex set;*
- (2) *If problem (NP_{EF}) is a strictly quasi- (E, F) -convex programming and \bar{x} is a local solution of (NP_{EF}) , then \bar{x} is the unique global solution.*

Proof. (1) For any $\bar{x}, \bar{y} \in \Omega_{EF}$ and any $\lambda \in (0, 1)$, we have $\bar{x} \in E(M) \cap F(M)$, $\bar{y} \in E(M) \cap F(M)$. Since $E(M) \cap F(M)$ is a convex set, we can get $\lambda \bar{x} + (1 - \lambda)\bar{y} \in E(M) \cap F(M)$, so there exist $x, y \in M$ such that $\bar{x} \in E(x)$, $\bar{y} \in F(y)$. Let f^* be the optimal value of (NP_{EF}) . Obviously, $f(\bar{x}) = f(\bar{y}) = f^*$. Since f is quasi- (E, F) -convex on M , we have

$$f(\lambda \bar{x} + (1 - \lambda)\bar{y}) \leq \max\{f(\bar{x}), f(\bar{y})\} = f^*.$$

It means that $\lambda \bar{x} + (1 - \lambda)\bar{y}$ is a global solution of (NP_{EF}) , so $\lambda \bar{x} + (1 - \lambda)\bar{y} \in \Omega_{EF}$, i.e., Ω_{EF} is a convex set.

(2) At first, we prove that \bar{x} is a global solution of problem (NP_{EF}) . Suppose, by contradiction, that \bar{x} is not a global solution of problem (NP_{EF}) . So there exists $\bar{y} \in E(M) \cap F(M)$ ($\bar{y} \neq \bar{x}$) such that $f(\bar{y}) < f(\bar{x})$. According to $\bar{x} \in E(M) \cap F(M)$, $\bar{y} \in E(M) \cap F(M)$, there exist $x \in M, y \in M$, such that $\bar{x} \in E(x)$, $\bar{y} \in F(y)$. Therefore, we have by the strict quasi- (E, F) -convexity of f

$$f(\lambda \bar{y} + (1 - \lambda)\bar{x}) < \max\{f(\bar{y}), f(\bar{x})\} = f(\bar{x}), \forall \lambda \in [0, 1]. \tag{5}$$

Taking into account $\lambda \bar{y} + (1 - \lambda)\bar{x} \in E(M) \cap F(M)$ and $\lambda \bar{y} + (1 - \lambda)\bar{x} \rightarrow \bar{x}$ ($\lambda \rightarrow 0^+$) we know that for λ small enough, the inequality (5) contradicts the fact that \bar{x} is a local solution. Therefore, \bar{x} is a global solution.

Secondly, we prove the uniqueness. If the conclusion is not true, then there exists $\hat{y} \in E(M) \cap F(M)$ ($\hat{y} \neq \bar{x}$) such that $f(\hat{y}) = f(\bar{x})$. Further, there exist

$x, y \in M$ such that $\bar{x} \in E(x), \hat{y} \in F(y)$. Since f is a strictly quasi-(E, F)-convex, we have $f(\lambda\hat{y} + (1 - \lambda)\bar{x}) < \max\{f(\hat{y}), f(\bar{x})\} = f(\bar{x})$. Noting that $\lambda\hat{y} + (1 - \lambda)\bar{x} \in E(M) \cap F(M)$. This contradicts the fact that \bar{x} is an optimal solution. Thus, \bar{x} is the unique global solution. \square

Theorem 3.4. *Let $M \subseteq R^n$ be an (E, F)-convex set, x^* be a local solution of (NP). If f is strictly quasi-(E, F)-convex and E, F are contractive maps on M , $x^* \in E(x^*)$, then x^* is the unique global optimal solution of problem (NP).*

Proof. We first prove that x^* is a global solution. If it is not true, then there exists $y^* \in M (y^* \neq x^*)$ such that $f(y^*) < f(x^*)$. Since f is a strict quasi-(E, F)-convex function and E, F are contractive maps on M , one has for any $\bar{x} \in E(x^*), \bar{y} \in F(y^*)$ and $\lambda \in (0, 1)$

$$f(\lambda\bar{y} + (1 - \lambda)\bar{x}) < \max\{f(\bar{x}), f(\bar{y})\} \leq \max\{f(x^*), f(y^*)\} \leq f(x^*). \tag{6}$$

Noting that $x^* \in E(x^*)$, we take $\bar{x} = x^*$ and obtain $\lambda\bar{y} + (1 - \lambda)x^* \in M, f(\lambda\bar{y} + (1 - \lambda)x^*) < f(x^*)$. By taking $\lambda \rightarrow 0^+$, we can get $\lambda\bar{y} + (1 - \lambda)x^* \rightarrow x^*$. This contradicts the fact that x^* is a local solution. Hence, x^* is a global solution.

Secondly, we prove the uniqueness. If there exists $y^* (y^* \neq x^*)$ such that $f(y^*) = f(x^*)$. Similar to (6), we have for any $\bar{x} \in E(x^*), \bar{y} \in F(y^*)$ and $\lambda \in (0, 1)$

$$f(\lambda\bar{x} + (1 - \lambda)\bar{y}) < \max\{f(\bar{x}), f(\bar{y})\} \leq \max\{f(x^*), f(y^*)\} = f(x^*). \tag{7}$$

Since M is an (E, F)-convex set, $\lambda\bar{x} + (1 - \lambda)\bar{y} \in M$. So the inequality (7) contradicts the fact that x^* is a global solution. Thus, x^* is the unique global optimal solution of problem (NP). \square

4. Optimality Conditions

In this section, we further extend the concept of quasi-(E, F)-convex function, then discuss the optimality conditions of the corresponding programming. We will consider the following nonlinear programming problems with inequality constraints:

$$(P_g) \quad \begin{aligned} &\min && f(x) \\ &\text{s.t.} && g_i(x) \leq 0, \quad i \in I = \{1, 2, \dots, m\}, \end{aligned}$$

where $f, g_i (i \in I)$ are continuously differentiable on R^n .

Denote the feasible set of (P_g) by $M_g = \{x \in R^n : g_i(x) \leq 0, i \in I\}$.

Definition 4.1. Let M be a nonempty open set in R^n and $f : M \rightarrow R$ be differentiable on M . The function f is said to be pseudo- (E, F) -convex on M if for each $x, y \in M, \forall \bar{x} \in E(x), \forall \bar{y} \in F(y)$ with $\nabla f(\bar{x})^T(\bar{y} - \bar{x}) \geq 0$ we have $f(\bar{y}) \geq f(\bar{x})$; or, equivalently, if $f(\bar{y}) < f(\bar{x})$, then $\nabla f(\bar{x})^T(\bar{y} - \bar{x}) < 0$.

Theorem 4.2. Let M be a nonempty open and (E, F) -convex set in R^n . If f is (E, F) -convex on M , then f also is pseudo- (E, F) -convex on M .

Proof. Suppose that $\nabla f(\bar{x})^T(\bar{y} - \bar{x}) \geq 0$, for any $x, y \in M, \forall \bar{x} \in E(x), \forall \bar{y} \in F(y)$.

Since f is (E, F) -convex on M , we have

$$f(\lambda\bar{y} + (1 - \lambda)\bar{x}) \leq \lambda f(\bar{y}) + (1 - \lambda)f(\bar{x}), \forall \lambda \in (0, 1). \tag{8}$$

By Taylor expansion, we have

$$f(\lambda\bar{y} + (1 - \lambda)\bar{x}) = f(\bar{x}) + \lambda \nabla f(\bar{x})^T(\bar{y} - \bar{x}) + o(\lambda). \tag{9}$$

We obtain from (8) and (9)

$$f(\bar{y}) - f(\bar{x}) \geq \nabla f(\bar{x})^T(\bar{y} - \bar{x}) + \frac{o(\lambda)}{\lambda}.$$

Taking $\lambda \rightarrow 0^+$, we obtain

$$f(\bar{y}) - f(\bar{x}) \geq \nabla f(\bar{x})^T(\bar{y} - \bar{x}) \geq 0.$$

So $f(\bar{y}) \geq f(\bar{x})$, i.e., f is pseudo- (E, F) -convex on M . □

Theorem 4.3. (KKT Sufficient Conditions) Let x^* be a KKT point of problem (P_g) . Assume that there exists an ε -neighborhood $N_\varepsilon(x^*)$ about x^* , $\varepsilon > 0$, such that the function f is pseudo- (E, F) -convex and $g_i(x) (i = 1, 2, \dots, m)$ are quasi- (E, F) -convex over $N_\varepsilon(x^*)$. If E is a contractive map of function f and $g_i (i \in I)$ on M_g and $x^* \in F(x^*)$, then x^* is a local optimal solution of problem (P_g) .

Proof. For any $x \in M_g \cap N_\varepsilon(x^*)$, we have $g_i(x) \leq 0 = g_i(x^*), i \in I(x^*) = \{i \in I : g_i(x^*) = 0\}$. Since E is a contractive map of g_i , we have $g_i(\bar{x}) \leq g_i(x), \forall \bar{x} \in E(x)$. From the quasi- (E, F) -convexity of g_i and $x^* \in F(x^*)$, we obtain

$$g_i(\lambda\bar{x} + (1 - \lambda)x^*) \leq \max\{g_i(\bar{x}), g_i(x^*)\} = 0, \forall \lambda \in (0, 1), i \in I(x^*).$$

On the other hand, by the differentiability of $g_i(x)$, one has

$$0 \geq g_i(\lambda\bar{x} + (1 - \lambda)x^*) = g_i(x^*) + \lambda \nabla g_i(x^*)^T(\bar{x} - x^*) + o(\lambda).$$

Noting that $g_i(x^*) = 0$ for $i \in I(x^*)$, one gets

$$\lambda \nabla g_i(x^*)^T(\bar{x} - x^*) + o(\lambda) \leq 0, \quad i \in I(x^*).$$

Dividing the above inequality by λ and taking $\lambda \rightarrow 0^+$, we have

$$\nabla g_i(x^*)^T(\bar{x} - x^*) \leq 0, \quad i \in I(x^*).$$

Since x^* is a KKT point, there exist multipliers $u_i \geq 0$, $i \in I(x^*)$ such that

$$\nabla f(x^*) + \sum_{i \in I(x^*)} u_i \nabla g_i(x^*) = 0,$$

further, we obtain

$$\nabla f(x^*)^T(\bar{x} - x^*) = - \sum_{i \in I(x^*)} u_i \nabla g_i(x^*)^T(\bar{x} - x^*) \geq 0.$$

Since f is pseudo- (E, F) -convex and E is a contractive map of f , we can conclude $f(x) \geq f(\bar{x}) \geq f(x^*)$. Therefore, x^* is a local optimal solution of (P_g) . The proof is complete. \square

Corollary 4.4. *Let x^* be a KKT point of problem (P_g) . Suppose that $f(x)$, $g_i(x)$ ($i \in I$) are all (E, F) -convex functions on $N_\varepsilon(x^*)$. If $x^* \in E(x^*) \cup F(x^*)$, E, F are contractive maps of function f and g_i ($i \in I$) on M_g , then x^* is a local optimal solution of (P_g) .*

Proof. We have $x^* \in E(x^*)$ or $x^* \in F(x^*)$ from $x^* \in E(x^*) \cup F(x^*)$.

Case A. $x^* \in F(x^*)$. The conclusion holds true from Theorem 4.3.

Case B. $x^* \in E(x^*)$.

For any $x \in M_g \cap N_\varepsilon(x^*)$, from Theorem 4.3, we know $g_i(x)$ ($i \in I$) are quasi- (E, F) -convex functions, thus,

$$g_i(\lambda \bar{x} + (1 - \lambda)x^*) \leq \max\{g_i(\bar{x}), g_i(x^*)\}, \quad x^* \in E(x^*), \quad \forall \bar{x} \in F(x).$$

Since E, F are contractive maps of function g_i ($i \in I$) on M_g , we have

$$\max\{g_i(\bar{x}), g_i(x^*)\} \leq \max\{g_i(x), g_i(x^*)\} = 0, \quad i \in I(x^*).$$

Therefore,

$$0 \geq g_i(\lambda \bar{x} + (1 - \lambda)x^*) = g_i(x^*) + \lambda \nabla g_i(x^*)^T(\bar{x} - x^*) + o(\lambda)$$

$$= \lambda \nabla g_i(x^*)^T (\bar{x} - x^*) + o(\lambda), \quad i \in I(x^*).$$

Dividing by λ and taking $\lambda \rightarrow 0^+$, one gets

$$\nabla g_i(x^*)^T (\bar{x} - x^*) \leq 0, \quad i \in I(x^*).$$

Since x^* is a KKT point of (P_g) , we have

$$\nabla f(x^*)^T (\bar{x} - x^*) = - \sum_{i \in I(x^*)} u_i \nabla g_i(x^*)^T (\bar{x} - x^*) \geq 0.$$

Noting that the (E, F) -convexity of f , one knows from Theorem 4.2 that f is quasi- (E, F) -convex, so $f(\bar{x}) \geq f(x^*)$. On the other hand, one has $f(\bar{x}) \leq f(x)$, $\forall \bar{x} \in E(x)$ due to the fact that F is a contractive map of function f on M_g . Therefore,

$$f(x^*) \leq f(x).$$

It indicates that x^* is a local optimal solution of (P_g) . The proof is complete.

□

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