

GENERALIZED DICHOTOMY FOR ORDINARY
DIFFERENTIAL EQUATIONS IN A BANACH SPACE

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Abstract: A dichotomy similar property for a class of homogeneous differential equations in an arbitrary Banach space is introduced. By help of them, existence of quasi bounded solutions of the appropriate nonhomogeneous equation is proved. A special roughness for such equations is considered.

AMS Subject Classification: 34G10, 34G20

Key Words: ordinary differential equations, generalized dichotomy

1. Introduction

The notion of exponential and ordinary dichotomy is fundamental in the qualitative theory of ordinary differential equations. It is considered in detail for example in the monographs [3]-[7].

In the given paper we introduce a (M, N, R) dichotomy, which is a generalisation of all dichotomies known by the authors. The aim of these paper is the research of this dichotomy and the connection between it and the existence of a special kind of solutions of the related nonhomogeneous differential equation.

A special kind of roughness of the (M, N, R) dichotomy is introduced and considered. Example for an equation, who is (M, N, R) dichotomous but not classical dichotomous is given.

2. Problem Statement

Let X be an arbitrary Banach space with norm $|\cdot|$ and identity I and let $J = [c, \infty)$ where $c \in \mathbb{R}$. Let $L(X)$ be the space of all linear bounded operators acting in X with the norm $\|\cdot\|$.

We consider the linear equation

$$\frac{dx}{dt} = A(t)x, \quad (1)$$

where $A(t) \in L(X), t \in J$.

By $V(t)$ we will denote the Cauchy operator of (1).

We consider the nonhomogeneous equation

$$\frac{dx}{dt} = A(t)x + f(t). \quad (2)$$

We say that the operators $D_1(t), D_2(t) : X \rightarrow X (t \in J)$ and the function $f(t) : J \rightarrow X (t \in J)$ satisfy the condition (H1) if the follow relation

$$(H1). f(t) \in \text{Fix} V(t)(D_1(t) + D_2(t)) (t \in J)$$

is fulfilled. By $\text{Fix} T$ we denote the set of all fixed points of the map $T, T : X \rightarrow X$.

Remark 1. The condition (H1) is automatically fulfilled if for example $D_1(t) = R_1(t)V^{-1}(t), D_2(t) = R_2(t)V^{-1}(t)$, where $R_1(t) + R_2(t) = I$.

Proof. We have

$$V(t)(D_1(t) + D_2(t))f(t) = f(t).$$

□

Lemma 1. *Let the condition (H1) holds. Then the function*

$$x(t) = \int_c^t V(t)D_1(s)f(s)ds - \int_t^\infty V(t)D_2(s)f(s)ds \quad (3)$$

is a solution of the equation (2) if the integrals in (3) exist.

Proof.

$$\frac{dx}{dt} = A(t) \int_c^t V(t)D_1(s)f(s)ds + V(t)D_1(t)f(t) + V(t)D_2(t)f(t)$$

$$- A(t) \int_t^\infty V(t)D_2(s)f(s)ds,$$

$$\frac{dx}{dt} = A(t)x(t) + V(t)D_1(t)f(t) + V(t)D_2(t)f(t),$$

$$\frac{dx}{dt} = A(t)x(t) + (V(t)D_1(t) + V(t)D_2(t))f(t),$$

$$\frac{dx}{dt} = A(t)x(t) + V(t)(D_1(t) + D_2(t))f(t),$$

$$\frac{dx}{dt} = A(t)x(t) + f(t).$$

□

We introduce the following conditions

$$(H2) \quad | V(t)D_1(s)z | \leq M(t, s, z), t \geq s, z \in X,$$

$$(H3) \quad | V(t)D_2(s)z | \leq N(t, s, z), t < s, z \in X.$$

For many important cases the right hand part of (H2) and (H3) has the form

$$\begin{cases} M(t, s, z) = \varphi_1(t)\varphi_2(s) | z |, & (t \geq s), z \in X \\ N(t, s, z) = \psi_1(t)\psi_2(s) | z |, & (t < s), z \in X \end{cases} \tag{4}$$

where $\varphi_1(t), \varphi_2(t), \psi_1(t), \psi_2(t)$ are positive scalar functions. We set

$$\alpha(t) = \max_{t \in J} \{ \varphi_1(t), \psi_1(t) \},$$

$$\mu(t) = \min_{t \in J} \{ \varphi_1(t), \psi_1(t) \},$$

$$\beta(t) = \max_{t \in J} \{ \varphi_2(t), \psi_2(t) \}.$$

Definition 1. We call the equation (1) be (D_1, D_2, M, N) dichotomous if the conditions (H2), (H3) are fulfilled.

Such kind of dichotomy can be used for consideration of some equations in [1].

Definition 2. We call the equation (1) be (M, N, R) dichotomous if it is (D_1, D_2, M, N) dichotomous with

$$D_1(t) = R(t)V^{-1}(t),$$

$$D_2(t) = (I - R(t))V^{-1}(t),$$

where $R(t) : X \rightarrow X$ ($t \in J$) is an arbitrary bounded operator.

Let $a(t)$ is an arbitrary positive scalar function. We consider the following Banach spaces :

$$K_a = \{g : J \rightarrow X : \sup_{t \in J} a(t) \int_c^t M(t, s, g(s)) ds < \infty\}$$

with the norm

$$\|g\|_{K_a} = \sup_{t \in J} a(t) \int_c^t M(t, s, g(s)) ds,$$

$$L_a = \{g : J \rightarrow X : \sup_{t \in J} a(t) \int_t^\infty N(t, s, g(s)) ds < \infty\}$$

with the norm

$$\|g\|_{L_a} = \sup_{t \in J} a(t) \int_t^\infty N(t, s, g(s)) ds,$$

$$C_a = \{g : J \rightarrow X : \sup_{t \in J} a(t) |g(t)| < \infty\}$$

with the norm

$$\|g\|_{C_a} = \sup_{t \in J} a(t) |g(t)|$$

and

$$T_a = \{g : J \rightarrow X : \int_c^\infty a(s) |g(s)| ds < \infty\}$$

with the norm

$$\|g\|_{T_a} = \int_c^\infty a(s) |g(s)| ds.$$

3. Main Results

3.1. Estimates of the Solutions of (1) and (2)

Theorem 1. *Let the equation (1) is (D_1, D_2, M, N) - dichotomous and let $D_1(t), D_2(t)$ and $f(t)$ fulfilled the condition (H1). Then for every function $f \in K_a \cap L_a$ the equation (2) has a solution in the space C_a .*

Proof. From Lemma 1 it follows

$$x(t) = \int_c^t V(t)D_1(s)f(s)ds - \int_t^\infty V(t)D_2(s)f(s)ds$$

$$|x(t)| \leq \int_c^t |V(t)D_1(s)f(s)|ds + \int_t^\infty |V(t)D_2(s)f(s)|ds$$

$$a(t)|x(t)| \leq a(t) \int_c^t M(t, s, f(s))ds + a(t) \int_t^\infty N(t, s, f(s))ds < \infty$$

□

Corollary 1. *Let the following conditions are fulfilled:*

1. *The equation (1) be (D_1, D_2, M, N) - dichotomous of the form (4).*
2. *The operators $D_1(t), D_2(t)$ and the function $f(t)$ satisfy the condition (H1).*

Then for every function $f \in K_{\mu^{-1}} \cap L_{\mu^{-1}}$ the equation (2) has a solution in the space $C_{\alpha^{-1}}$ and the following estimate holds

$$\sup_{t \in J} \alpha^{-1}(t) |x(t)| \leq \int_c^t \beta(s) |f(s)| ds + \int_t^\infty \beta(s) |f(s)| ds < \infty$$

Proof. From Theorem 1 and the presentation (4) it follows

$$\mu^{-1}(t)|x(t)| \leq \mu^{-1}(t)\varphi_1(t) \int_c^t \varphi_2(s)|f(s)|ds + \mu^{-1}(t)\psi_1(t) \int_t^\infty \psi_2(s)|f(s)|ds < \infty$$

By multiplying by $\mu(t)\alpha(t)^{-1} \leq 1$ the left side and the one addent of the right side, whose multiplier in front of the integral is not equal to 1, we receive

$$\alpha^{-1}(t) |x(t)| \leq \int_c^t \varphi_2(s) |f(s)| ds + \int_t^\infty \psi_2(s) |f(s)| ds \leq$$

$$\leq \int_c^t \beta(s) |f(s)| ds + \int_t^\infty \beta(s) |f(s)| ds < \infty$$

□

Theorem 2. *Let the equation (1) is (M, N, R) - dichotomous. Then following estimates hold*

$$|x_1(t)| \leq M(t, s, x_1(s)), \quad t \geq s \geq c \tag{5}$$

for all solutions $x_1(t)$ of (1) , $(t \geq c)$, which started in the set

$$\bigcap_{s \in J} \text{Fix } R(s)$$

and

$$|x_2(t)| \leq N(t, s, x_2(s)), \quad c \leq t < s \tag{6}$$

for all solutions $x_2(t)$ of (1) ,($t \geq c$), which started in the set

$$\bigcap_{s \in J} \text{Fix}(I - R(s))$$

Proof. The equalities

$$x_1(t) = V(t)x_1(c) = V(t)R(s)x_1(c) = V(t)R(s)V^{-1}(s)x_1(s)$$

imply following estimates

$$|x_1(t)| = |V(t)R(s)V^{-1}(s)x_1(s)| \leq M(t, s, x_1(s)), \quad (t \geq s)$$

The proof of (6) is analogously. □

3.2. Roughness

We shall introduce and consider a special kind of roughness typical for (M, N, R) dichotomous equations.

Let Z be an arbitrary Banach space. In the set of all subspaces of Z we can define following metric (see [5]):

$$\rho(Z_1, Z_2) = \rho_H(\Sigma(Z_1), \Sigma(Z_2)) \tag{7}$$

where $\Sigma(Y)$ ($Y \subset Z$) denotes the unit ball of the subspace Y and ρ_H is the Hausdorff metric.

We consider the following equation

$$\frac{dx}{dt} = B(t)x \tag{8}$$

Theorem 3. *Let the following conditions are fulfilled:*

1. *The equation (1) is (M, N, R) - dichotomous of the form (4).*
2. *$R(t)$ is continuous operator for every $t \in J$ and*

$$(R(t') - R(t''))x \xrightarrow{t'' \rightarrow t'} 0$$

uniformly for every bounded subset of X and $t', t'' \in J$.

Then for every $\epsilon > 0$ there exists a $\bar{\delta} > 0$ such that for $\delta \in (0, \bar{\delta})$ all equations (8), for which

$$\sup_{t \in J} |(A(t) - B(t))x| \leq \delta|x| \quad (x \in X)$$

are $(\tilde{M}, \tilde{N}, \tilde{R})$ dichotomous and $\rho_1(C_{\alpha-1}, C_{\bar{\alpha}-1}), \rho_2(T_\beta, T_{\bar{\beta}}) \leq \epsilon$, where the functions \tilde{M}, \tilde{N} , the operator \tilde{R} and the Banach spaces $C_{\alpha-1}, C_{\bar{\alpha}-1}, T_\beta, T_{\bar{\beta}}$ will be defined below and ρ_1, ρ_2 are metrics from (7).

Proof. Let $\tilde{V}(t)$ is the Cauchy operator of (8). Let $R_1 = R$ and $R_2 = I - R$. For sufficiently small $\bar{\delta} > 0$ the numbers

$$|V(t)R_i(s)V^{-1}(s)z| \quad \text{and} \quad |\tilde{V}(t)\tilde{R}_i(s)\tilde{V}^{-1}(s)z| \quad (i = 1, 2)$$

will have an arbitrary small difference for

$$|R_i(s)V^{-1}(s)z - \tilde{R}_i(s)\tilde{V}^{-1}(s)z| \leq \delta |z|, \quad (z \in X), \quad (i = 1, 2), \quad \delta \in (0, \bar{\delta}), \quad (s \geq c)$$

by suitable choice of $\tilde{R}_i(s)$ (for example if $\tilde{R}_i(s) = R_i(s)V^{-1}(s)\tilde{V}(s)$).

Because (1) is (M, N, R) - dichotomous of the form (4), we can find functions $\tilde{\varphi}_1, \tilde{\varphi}_2, \tilde{\psi}_1, \tilde{\psi}_2$ arbitrary close to $\varphi_1, \varphi_2, \psi_1, \psi_2$ respectively, for which

$$|\tilde{V}(t)\tilde{R}_1(s)\tilde{V}^{-1}(s)z| \leq \tilde{\varphi}_1(t)\tilde{\varphi}_2(s) |z| \quad (t \geq s), \quad z \in X$$

$$|\tilde{V}(t)\tilde{R}_2(s)\tilde{V}^{-1}(s)z| \leq \tilde{\psi}_1(t)\tilde{\psi}_2(s) |z| \quad (s \geq t), \quad z \in X$$

i.e. $\tilde{M}(t, s, z) = \tilde{\varphi}_1(t)\tilde{\varphi}_2(s)|z|$ and $\tilde{N}(t, s, z) = \tilde{\psi}_1(t)\tilde{\psi}_2(s)|z|$.

Let

$$\tilde{\alpha}(t) = \max_{t \in J} \{ \tilde{\varphi}_1(t), \tilde{\psi}_1(t) \}$$

and

$$\tilde{\beta}(t) = \max_{t \in J} \{ \tilde{\varphi}_2(t), \tilde{\psi}_2(t) \}.$$

We choose a function

$$a(t) \geq \max_{t \in J} \{ \alpha(t), \tilde{\alpha}(t) \}$$

and consider the Banach space C_{a-1} . Obviously $C_{\alpha-1}$ and $C_{\tilde{\alpha}-1}$ are subsets of C_{a-1} . By straightforward verification we will prove that $C_{\alpha-1}$ and $C_{\tilde{\alpha}-1}$ are closed in C_{a-1} , i.e. they are subspaces of C_{a-1} .

Indeed, first we shall prove, that $C_{\alpha-1}$ is closed in C_{a-1} , when $a(t) > \alpha(t)$.

Let

$$\lim_{n \rightarrow \infty} |g_n - g|_{C_{a-1}} = 0$$

and let $g_n \in C_{a-1}$. We will prove, that $g \in C_{a-1}$. We have

$$\lim_{n \rightarrow \infty} \left(\sup_{t \in J} \frac{|g_n(t) - g(t)|}{a(t)} \right) = 0, \quad \text{i.e.} \quad \lim_{n \rightarrow \infty} \left(\sup_{t \in J} |g_n(t) - g(t)| \right) = 0$$

and

$$\sup_{t \in J} \frac{|g_n(t)|}{\alpha(t)} < \infty \quad (n \in N).$$

Then from

$$\frac{|g(t)|}{\alpha(t)} \leq \frac{|g_n(t)|}{\alpha(t)} + \frac{|g(t) - g_n(t)|}{\alpha(t)}$$

we obtain

$$\lim_{t \in J} \frac{|g(t)|}{\alpha(t)} \leq \lim_{t \in J} \frac{|g_n(t)|}{\alpha(t)} + \lim_{t \in J} \frac{|g(t) - g_n(t)|}{\alpha(t)} < \infty$$

Hence $g \in C_{\alpha^{-1}}$, i.e. $C_{\alpha^{-1}}$ is closed in $C_{a^{-1}}$.

The proof for $C_{\tilde{\alpha}^{-1}}$ is analogously.

Let ρ_1 is the metric in the set of all subspaces of $C_{a^{-1}}$. To show that $\rho_1(C_{\alpha^{-1}}, C_{\tilde{\alpha}^{-1}}) = \rho_H(\Sigma(C_{\alpha^{-1}}), \Sigma(C_{\tilde{\alpha}^{-1}})) \leq \epsilon$ it is necessary and sufficient that for every element $g \in \Sigma(C_{\alpha^{-1}})$ there exists an element $h \in \Sigma(C_{\tilde{\alpha}^{-1}})$, such that $|g - h|_{C_{a^{-1}}} \leq \epsilon$ and vice versa.

We choose $\bar{\delta}$ so small, that

$$\sup_{t \in J} |\alpha(t) - \tilde{\alpha}(t)| = \eta \leq \Delta \epsilon$$

where

$$\Delta = \min\{\inf_{t \in J} \alpha(t), \inf_{t \in J} \tilde{\alpha}(t)\}$$

Without loss of generality we may assume that $\Delta > 0$, $\epsilon < 1$. Then we have

$$\alpha(t) - \eta \leq \tilde{\alpha}(t) \leq \alpha(t) + \eta \tag{9}$$

Let $g \in \Sigma(C_{\alpha^{-1}})$ is an arbitrary element, i.e.

$$\sup_{t \in J} \frac{|g(t)|}{\alpha(t)} \leq 1, \quad \sup_{t \in J} \frac{|g(t)|}{\alpha(t)} < \infty$$

We take

$$h(t) = \frac{\alpha(t) - \eta}{\alpha(t)} g(t)$$

Then $h \in C_{\tilde{\alpha}^{-1}}$ because

$$\sup_{t \in J} \frac{|h(t)|}{\tilde{\alpha}(t)} = \sup_{t \in J} \frac{(\alpha(t) - \eta)|g(t)|}{\tilde{\alpha}(t)\alpha(t)} \leq \sup_{t \in J} \frac{(\tilde{\alpha}(t) + \eta - \eta)|g(t)|}{\tilde{\alpha}(t)\alpha(t)} = \sup_{t \in J} \frac{|g(t)|}{\alpha(t)} < \infty$$

We have $h \in \Sigma(C_{\tilde{\alpha}^{-1}})$ because

$$|h|_{C_{a^{-1}}} \leq |g|_{C_{a^{-1}}} \sup_{t \in J} \frac{|\alpha(t) - \eta|}{\alpha(t)} \leq |g|_{C_{a^{-1}}} \leq 1$$

And $|g - h|_{C_{a^{-1}}} \leq \epsilon$ because from

$$\frac{|g(t) - h(t)|}{a(t)} = \frac{1}{a(t)} \left| 1 - \frac{\alpha(t) - \eta}{\alpha(t)} \right| |g(t)|$$

we obtain

$$|g - h|_{C_{a^{-1}}} = \sup_{t \in J} \frac{|g(t) - h(t)|}{a(t)} = \sup_{t \in J} \frac{|g(t)|}{a(t)} \frac{\eta}{\alpha(t)} \leq |g|_{C_{a^{-1}}} \eta \sup_{t \in J} \frac{1}{\alpha(t)} \leq \frac{\Delta \epsilon}{\Delta} = \epsilon$$

Now vice versa - let $h \in \Sigma(C_{\tilde{\alpha}^{-1}})$ is an arbitrary element, i.e.

$$\sup_{t \in J} \frac{|h(t)|}{a(t)} \leq 1, \quad \sup_{t \in J} \frac{|h(t)|}{\tilde{\alpha}(t)} < \infty$$

We take

$$g(t) = \frac{\tilde{\alpha}(t) - \eta}{\tilde{\alpha}(t)} h(t)$$

Then $g \in C_{\alpha^{-1}}$ because

$$\sup_{t \in J} \frac{|g(t)|}{\alpha(t)} = \sup_{t \in J} \frac{(\tilde{\alpha}(t) - \eta) |h(t)|}{\tilde{\alpha}(t) \alpha(t)} \leq \sup_{t \in J} \frac{|h(t)|}{\tilde{\alpha}(t)} < \infty$$

We have $g \in \Sigma(C_{\alpha^{-1}})$ because

$$|g|_{C_{\alpha^{-1}}} = \frac{|g(t)|}{a(t)} \leq |h|_{C_{a^{-1}}} \sup_{t \in J} \frac{|\tilde{\alpha}(t) - \eta|}{\tilde{\alpha}(t)} \leq |h|_{C_{a^{-1}}} \leq 1$$

And $|g - h|_{C_{a^{-1}}} \leq \epsilon$ because from

$$\frac{|g(t) - h(t)|}{a(t)} = \frac{1}{a(t)} \left| \frac{\tilde{\alpha}(t) - \eta}{\tilde{\alpha}(t)} - 1 \right| |h(t)| = \frac{|h(t)|}{a(t)} \frac{\eta}{\tilde{\alpha}(t)}$$

we obtain

$$|g - h|_{C_{a^{-1}}} = \sup_{t \in J} \frac{|g(t) - h(t)|}{a(t)} \leq |h|_{C_{a^{-1}}} \eta \sup_{t \in J} \frac{1}{\tilde{\alpha}(t)} \leq \frac{\Delta \epsilon}{\Delta} = \epsilon$$

Hence $\rho_1(C_{\alpha^{-1}}, C_{\tilde{\alpha}^{-1}}) \leq \epsilon$.

Now we choose a function

$$b(t) < \min_{t \in J} \{\beta(t), \tilde{\beta}(t)\}$$

and consider the Banach space T_b .

It is not difficult to show that T_β and $T_{\tilde{\beta}}$ are closed in T_b and hence they are subspaces of T_b .

Let ρ_2 is the metric in the set of all subspaces of T_b . We choose $\bar{\delta}$ so small, that

$$\sup_{t \in J} |\beta(t) - \tilde{\beta}(t)| \leq \epsilon$$

Hence

$$\beta(t) - \epsilon \leq \tilde{\beta}(t) \leq \beta(t) + \epsilon \quad (10)$$

Let $g \in \Sigma(T_\beta)$ be an arbitrary element, i.e.

$$\int_J \beta(t) |g(t)| dt < \infty, \quad \int_J b(t) |g(t)| dt \leq 1$$

We are searching for an element $h \in \Sigma(T_{\tilde{\beta}})$, such that $|g - h|_{T_b} \leq \epsilon$.

We set

$$h(t) = \frac{\beta(t)}{\beta(t) + \epsilon} g(t)$$

Then $h \in T_{\tilde{\beta}}$ because from (10) we have

$$\int_J \tilde{\beta}(t) |h(t)| dt = \int_J \tilde{\beta}(t) \frac{\beta(t)}{\beta(t) + \epsilon} |g(t)| dt \leq \int_J \frac{\beta(t) + \epsilon}{\beta(t) + \epsilon} \beta(t) |g(t)| dt < \infty$$

Also $h \in \Sigma(T_{\tilde{\beta}})$ because

$$\int_J b(t) \frac{\beta(t)}{\beta(t) + \epsilon} |g(t)| dt \leq \int_J b(t) |g(t)| dt \leq 1$$

Without loss of generality we may assume that $\beta(t) \geq 1$ ($t \in J$). Then $|g - h|_{T_b} \leq \epsilon$ because

$$\int_J b(t) |g(t) - \frac{\beta(t)}{\beta(t) + \epsilon} g(t)| dt = \int_J b(t) |g(t)| \left| \frac{\epsilon}{\beta(t) + \epsilon} \right| dt \leq \epsilon \int_J b(t) |g(t)| dt \leq \epsilon$$

Now vice versa - let $h \in \Sigma(T_{\tilde{\beta}})$ is an arbitrary element, i.e.

$$\int_J \tilde{\beta}(t) |h(t)| dt < \infty, \quad \int_J b(t) |h(t)| dt \leq 1$$

We are searching for an element $g \in \Sigma(T_\beta)$, such that $|h - g|_{T_b} \leq \epsilon$.

We set

$$g(t) = \frac{\tilde{\beta}(t)}{\tilde{\beta}(t) + \epsilon} h(t)$$

From (10) follows

$$\tilde{\beta}(t) - \epsilon \leq \beta(t) \leq \tilde{\beta}(t) + \epsilon$$

Hence $g \in T_\beta$ because

$$\int_J \beta(t)|g(t)|dt = \int_J \beta(t) \frac{\tilde{\beta}(t)}{\tilde{\beta}(t) + \epsilon} |h(t)|dt \leq \int_J \tilde{\beta}(t)|h(t)|dt < \infty$$

And $g \in \Sigma(T_\beta)$ because

$$\int_J b(t) \frac{\tilde{\beta}(t)}{\tilde{\beta}(t) + \epsilon} |h(t)|dt \leq \int_J b(t)|g(t)|dt \leq 1$$

Without loss of generality we may assume that $\beta(t) \geq 1$ ($t \in J$). Then $\tilde{\beta}(t) + \epsilon \geq \beta(t) > 1$.

Then $|g - h|_{T_b} \leq \epsilon$ because

$$\int_J b(t)|h(t) - \frac{\tilde{\beta}(t)}{\tilde{\beta}(t) + \epsilon} h(t)|dt = \int_J b(t)|h(t)| \left| \frac{\epsilon}{\tilde{\beta}(t) + \epsilon} \right| dt \leq \epsilon \int_J b(t)|h(t)|dt \leq \epsilon$$

Hence $\rho_2(T_\beta, T_{\tilde{\beta}}) \leq \epsilon$. □

3.3. Considerations and an Example

Let $R(t) = P$, where $P : X \rightarrow X$ is a projector.

For

$$M(t, s, z) = K_1 e^{-\int_s^t \delta_1(\tau) d\tau} |z| \quad (t \geq s, z \in X)$$

$$N(t, s, z) = K_2 e^{-\int_t^s \delta_1(\tau) d\tau} |z| \quad (s > t, z \in X)$$

where K_1, K_2 are positive constants and δ_1, δ_2 are continuous real-valued functions on J , we obtain the exponential dichotomy of [6] :

$$\| V(t)PV^{-1}(s) \| \leq K_1 e^{-\int_s^t \delta_1(\tau) d\tau} \quad (t \geq s)$$

$$\| V(t)(I - P)V^{-1}(s) \| \leq K_2 e^{-\int_t^s \delta_2(\tau) d\tau} \quad (s > t).$$

For $\delta_i(t) = 0$ ($c \leq t < \infty, i = 1, 2$) we obtain the exponential dichotomy of [3],[4],[5], for which case we have $K_a \cap L_a = C_a$ by $a(t) \equiv 1$.

For

$$M(t, s, z) = Kh(t)h^{-1}(s)|z| \quad (t \geq s \geq c, z \in X)$$

$$N(t, s, z) = Kk(t)k^{-1}(s)|z| \quad (c \leq t \leq s, z \in X)$$

where K is a positive constant and $h, k : [0, \infty) \rightarrow (0, \infty)$ are two continuous functions, we obtain the dichotomy of [7]-[9]:

$$\| V(t)PV^{-1}(s) \| \leq Kh(t)h^{-1}(s) , (t \geq s \geq c)$$

$$\| V(t)(I - P)V^{-1}(s) \| \leq Kk(t)k^{-1}(s) , (c \leq t \leq s)$$

It may be also noted, that the dichotomies [2],[6]-[9] are a generalization of the dichotomy in [4].

Example. Let

$$\frac{dx}{dt} = a(t)x$$

where $X = \mathbb{R}$ and $a(t)$ is a piecewise continuous function. In this case we have

$$V(t) = \exp \int_c^t a(s)ds.$$

It is well known, that this equation in several cases is not dichotomous or exponential dichotomous.

For the conditions (H2) and (H3) we take respectively the forms

$$| V(t)r_1(s)V^{-1}(s)\xi | \leq \alpha(t)\beta(s)|\xi| \quad (t \geq s, \xi \in \mathbb{R}),$$

$$| V(t)r_2(s)V^{-1}(s)\xi | \leq \alpha(t)\beta(s)|\xi| \quad (t < s, \xi \in \mathbb{R}).$$

We set $r_1(t) + r_2(t) = 1, (t \geq c)$. Now we have

$$|r_1(s)V^{-1}(s)\xi| \leq \beta(s)|\xi|, \quad |r_2(s)V^{-1}(s)\xi| \leq \beta(s)|\xi|,$$

i.e. $\beta(t) \geq \max\{|r_1(t)V^{-1}(t)|, |r_2(t)V^{-1}(t)|\}$.

We take $\alpha(t) \geq |V(t)|, (t \geq c)$. Because condition (H1) holds,

$$x(t) = \int_c^t V(t)r_1(s)V^{-1}(s)f(s)ds - \int_t^\infty V(t)r_2(s)V^{-1}(s)f(s)ds$$

is a solution of the nonhomogeneous equation

$$\frac{dx}{dt} = a(t)x + f(t) .$$

For every positive function $b(t)$, the function $x(t)$ belongs to the space C_b for every $f \in L_b \cap K_b$.

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