

PI-1-1 NORMAL FORM IN A REGULAR CARDINAL

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Abstract: A normal form is given for Π_1^1 formulas over V_κ for a regular cardinal κ . Using it, a new characterization of weakly compact cardinals is given.

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1. Formulas

Normal form theorems for definable sets of reals are central to descriptive set theory. Here such will be considered for definable sets over V_κ where κ is a regular cardinal. In the case $\kappa = \omega$, the Ackerman coding [1] provides a definable bijection $V_\omega \mapsto \omega$, so V_ω could be used as the basic domain in this case.

Let L_\in denote the first order language of set theory, with binary relations $=, \in$. Let L_\in^s denote L_\in with set variables added, considered as unary predicate symbols (so $X(x)$ is an atomic formula). Let L_\in^f denote L_\in with function variables added, considered as unary function symbols (so $F(x)$ is a term).

For each of these languages, a bounded quantifier is one of the form $\forall x \in t$ or $\exists x \in t$, where t is a term (a variable in the case of L_\in or L_\in^s), such that x does not occur in t . A bounded, or Δ_0^0 , formula is a formula where all quantifiers

are bounded. For $n \geq 1$ a Σ_n^0 (Π_n^0) formula is a Δ_0^0 formula, preceded by n alternating blocks of first-order quantifiers, the first of which is \exists (\forall).

A Δ_0^1 formula is a formula which is Δ_0^0 , Σ_n^0 for some n , or Π_n^0 for some n . For $n \geq 1$ a Σ_n^1 (Π_n^1) formula is a Δ_0^1 formula, preceded by n alternating blocks of second-order quantifiers, the first of which is \exists (\forall). For $j = 1, 2$ the notation Σ_n^{js} is used for “ Σ_n^j over L_ϵ^s ”, etc.

Let $\text{Pow}(x)$ denote the power set of x . Let \mathcal{C} denote $\text{Pow}(V_\kappa)$. Formulas of L_ϵ^s may be considered as defining predicates in a Cartesian product of copies of V_κ and \mathcal{C} (a “product space”). Let \mathcal{N} denote $(V_\kappa)^{V_\kappa}$. Formulas of L_ϵ^f may be considered as defining predicates in a Cartesian product of copies of V_κ and \mathcal{N} .

Say that a predicate is Σ_n^j for $j = 1, 2$ (Π_n^j) if it is defined by a Σ_n^j (Π_n^j) formula. By predicate logic:

- Any of these classes is closed under \wedge and \vee .
- If P is Σ_n^j (Π_n^j) then $\neg P$ is Π_n^j (Σ_n^j)
- If $m > n$ then a Σ_n^j or Π_n^j predicate is both Σ_m^j and Π_m^j .

Various other closure properties may be shown; see [3] for example.

The notion of a Δ_n^j predicate is defined in the usual manner, and by a standard abuse of language, a Δ_n^j formula is a Σ_n^j or Π_n^j formula which defines a Δ_n^j predicate.

2. L_ϵ^s and L_ϵ^f

Lemma 1. *For any atomic formula ϕ of L_ϵ^f there is a Δ_1^0 formula ϕ' of L_ϵ^s such that $\phi(F_1, \dots, F_k)$ iff $\phi'(\gamma_{F_1}, \dots, \gamma_{F_k})$ where γ_F is the graph of F .*

Proof. In a standard manner, $t = u$ or $t \in u$ may be rewritten in a Δ_1^0 form involving only atomic formulas of the form $y = F(x)$, $w = x$, or $w \in x$. Now, $y = F(x)$ iff $\exists p(p = \langle x, y \rangle \wedge \gamma_F(p))$ iff $\forall p(p = \langle x, y \rangle \Rightarrow \gamma_F(p))$. Finally, $p = \langle x, y \rangle$ is Δ_0^0 . □

Lemma 2. *The predicate $\text{Func}(X)$ stating that X is the graph of a function is Π_2^{0s} .*

Proof. The formula $\forall x \exists p \exists y (p = \langle x, y \rangle \wedge X(p))$ states that X is total. The formula $\forall x \forall p_1 \forall p_2 \forall y_1 \forall y_2 (p_1 = \langle x, y_1 \rangle \wedge p_2 = \langle x, y_2 \rangle \wedge X(p_1) \wedge X(p_2) \Rightarrow p_1 = p_2)$ states that X is single-valued. □

Lemma 3. For any atomic formula ϕ of L_{\in}^s there is a Δ_0^f formula ϕ' of L_{\in}^f such that $\phi(X_1, \dots, X_k)$ iff $\phi'(\chi_{X_1}, \dots, \chi_{X_k})$ where χ_X is the characteristic function of X .

Proof. $X(x)$ iff $\chi_X(x) \neq 0$. □

Further facts can be stated; see for example theorems 15.XXV and 15.XXVI of [6] in the case of ω .

3. Normal Form

As in the case of ω , a normal form is more useful for formulas of L_{\in}^f (see [5] for example). In this case Skolem functions can be expressed in a simple manner. The notation \vec{x} is used to denote a sequence x_1, \dots, x_k of variables; $\exists \vec{x}$ denotes $\exists x_1 \cdots \exists x_k$, etc. A formula ϕ with free variables or parameters among \vec{F}, \vec{x} may be denoted $\phi(\vec{F}, \vec{x})$.

Theorem 4. If ϕ is a Δ_0^{1f} formula there is a Δ_0^{0f} formula ψ such that ϕ is equivalent to $\exists \vec{F} \forall \vec{x} \psi$ (in models of a suitable fragment of set theory for L_{\in}^f).

Proof. This is a refinement of the Skolem normal form theorem of Section 4.2 of [4]. Indeed, by this theorem ϕ can be written as $\exists F_1 \cdots \exists F_k \forall x_1 \cdots \forall x_l \psi_1$ where in ψ_1 F_i may have multiple arguments (where in fact ψ_1 can be taken as open).

This may be rewritten as $\exists \vec{F} \forall \vec{x} \forall \vec{y} (H_1 \wedge \cdots \wedge H_k \Rightarrow \psi_2)$, where H_i is $y_i = F_i(\vec{x}_i)$, \vec{x}_i is a subsequence of \vec{x} , and ψ_2 is ψ_1 with $F_i(\vec{x}_i)$ replaced by y_i .

Let H'_i be $x_{j_1} = 0 \wedge \cdots \wedge x_{j_i} \Rightarrow y_i = G_i(z)$, where the x_j are those not occurring in \vec{x} . The formula may be transformed to $\exists \vec{G} \forall \vec{x} \forall \vec{y} z (z = \langle x_1, \dots, x_l \rangle \wedge H'_1 \wedge \cdots \wedge H'_k \Rightarrow \psi_2)$. □

The models in which the theorem holds include V_{κ} for κ a cardinal.

Corollary 5. If ϕ is a Σ_1^{1f} formula there is a Δ_0^{0f} formula ψ such that ϕ is equivalent to $\exists \vec{F} \forall \vec{x} \psi$.

Proof. Transform the first order part to Skolem normal form, prepend the original existential function quantifiers, and proceed as in the proof of the theorem. □

Corollary 6. If ϕ is a Π_1^{1f} formula there is a Δ_0^{0f} formula ψ such that ϕ is equivalent to $\forall \vec{F} \exists \vec{x} \psi$.

Proof. Apply the preceding corollary to $\neg\phi$. □

$\exists\vec{F}\forall\vec{x}\psi$ may be transformed to $\exists F\forall x\psi$. Proceeding as in the proof of theorem 4, $\exists\vec{G}\forall\vec{x}\vec{y}z(z = \langle x_1, \dots, x_l \rangle \wedge H'_1 \wedge \dots \wedge H'_k \Rightarrow \psi_2)$ may be further transformed to $\exists G\forall\vec{x}\vec{y}\vec{w}zv(v = G(z) \wedge v = \langle w_1, \dots, w_k \rangle \wedge z = \langle x_1, \dots, x_l \rangle \wedge H''_1 \wedge \dots \wedge H''_k \Rightarrow \psi_2)$, where H''_i is $x_{j_1} = 0 \wedge \dots \wedge x_{j_t} \Rightarrow y_i = w_i$. Finally, a formula $\forall\vec{x}\psi$ may be transformed to $\forall u\forall\vec{x}(u = \langle x_1, \dots, x_l \rangle \Rightarrow \psi)$. The quantifier $\forall x_i$ may then be replaced by bounded quantifiers.

Suppose κ is a regular cardinal, $\phi(\vec{F})$ is a Δ_0^{of} formula over V_κ (possibly with first order parameters), and $u \in V_\kappa$. Let $\phi^{\upharpoonright u}$ denote ϕ with each occurrence of F_i replaced by $F_i \upharpoonright u$. This may be written in Δ_1^{of} form in a standard manner, as $\exists\vec{f}(f_1 = F_1 \upharpoonright u \wedge \dots \wedge f_k = F_k \upharpoonright u \wedge \phi(\vec{f}))$ and $\forall\vec{f}(f_1 = F_1 \upharpoonright u \wedge \dots \wedge f_k = F_k \upharpoonright u \Rightarrow \phi(\vec{f}))$.

For a Δ_0^{of} formula ψ with free variables \vec{x}, \vec{F} a predicate $Q_\psi(u, \vec{x}, \vec{F})$ will be defined by recursion on ψ , which holds iff the arguments of function applications are all in u . For a term t let Q_t is $\forall_s s \in u$ where s ranges over subterms other than t . $Q_{t=u} = Q_{t \in u} = Q_t \wedge Q_u$, $Q_{\neq\psi} = Q_\psi$, $Q_{\psi_1 \wedge \psi_2} = Q_{\psi_1 \vee \psi_2} = Q_{\psi_1} \wedge Q_{\psi_2}$, and $Q_{\exists x \in t \psi} = Q_{\forall x \in t \psi} = Q_t \wedge \forall x \in t Q_\psi$.

Lemma 7. *Suppose κ is a cardinal; then in V_κ , $Q_\psi \Rightarrow (\psi \Leftrightarrow \psi^{\upharpoonright u})$. If κ is regular, $\exists u Q_\psi$.*

Proof. The first claim follows by induction on ψ . The second claim does also, using regularity for the bounded quantifiers. □

4. Downsets

The notion of a tree is central to descriptive set theory. The generalization to a cardinal κ is better behaved if κ is assumed to be regular. Let $\mathcal{A} = \{f \in V_\kappa : f \text{ is a function}\}$; by the restriction on κ if a function $f : x \mapsto V_\kappa$ where $x \in V_\kappa$ then $f \in V_\kappa$.

\mathcal{A} is ordered by inclusion. A subset $D \subseteq \mathcal{A}$ is said to be a downset if, $f \in D$ and $g \subseteq f$ imply $g \in D$. If D is a downset a branch of D is a function $F \in \mathcal{N}$ such that $F \upharpoonright x \in D$ for all $x \in V_\kappa$. Let $[D]$ denote the set of branches of D . If $[D] \neq \emptyset$ say that D is branched; otherwise $[D]$ is unbranched.

\mathcal{A} may be generalized in a well-known manner. Let $\mathcal{A}^{(k)} = \{\vec{f} \in \mathcal{A}^k : \text{Dom}(f_1) = \dots = \text{Dom}(f_k)\}$ where $\text{Dom}(f)$ denotes the domain of the function f ; $\text{Dom}(\vec{f})$ may be written for the common domain. $\mathcal{A}^{(k)}$ may be ordered by ‘‘componentwise inclusion’’ $\vec{f} \subseteq_c \vec{g}$, which holds iff $f_i \subseteq g_i$ for all i . The

definition of a downset is essentially unchanged, and a branch is a vector \vec{F} which is a branch componentwise.

If D is a downset in \mathcal{A}^{k+l} and $\vec{G} \in \mathcal{N}^l$ let $D_{\@G} = \{\vec{f} : \langle \vec{f}, G_1 \upharpoonright \text{Dom}(\vec{f}), \dots, G_l \upharpoonright \text{Dom}(\vec{f}) \rangle \in D\}$. Note that $D_{\@G}$ is a downset.

A Δ_0^{0f} formula $\psi(\vec{F})$ may be translated to a Δ_0^{1f} formula $\psi'(\vec{f})$ in a well-known manner; by abuse of notation $\psi(\vec{f})$ will be written for this formula. The notation “ $\vec{x} \in_c u$ ” will be used for $x_1 \in u \wedge \dots \wedge x_t \in u$.

Theorem 8. *Suppose κ is a regular cardinal. Suppose ϕ is a formula $\forall \vec{F} \exists \vec{x} \psi(\vec{x}, \vec{F}, \vec{G})$ where ψ is Δ_0^{0f} (and for brevity has no first order parameters). Let*

$$D = \{\langle \vec{f}, \vec{g} \rangle \in \mathcal{A}^{k+l} : \forall \vec{x} \in_c \text{Dom}(\vec{f}) (Q_\psi(\text{Dom}(\vec{f}), \vec{x}, \vec{f}, \vec{g}) \Rightarrow \neg \psi(\vec{x}, \vec{f}, \vec{g}))\}.$$

Then D is a downset, and in V_κ , ϕ holds iff $D_{\@G}$ is unbranched.

Proof. It follows readily by induction on ψ that if $\langle \vec{f}', \vec{g}' \rangle \subseteq_c \langle \vec{f}, \vec{g} \rangle$ then $Q_\psi(\text{Dom}(\vec{f}'), \vec{x}, \vec{f}', \vec{g}') \Rightarrow Q_\psi(\text{Dom}(\vec{f}), \vec{x}, \vec{f}, \vec{g})$. It then follows that D is a downset. Using lemma 7 it follows readily that if ϕ is true then $D_{\@G}$ is unbranched; and conversely. \square

5. Weak Compactness

It is a well-known fact that a cardinal κ is weakly compact iff it is Π_1^1 -indescribable, that is, for any Π_1^{1s} sentence ϕ , if $\models_{V_\kappa} \phi$ then $\models_{V_\lambda} \phi$ for some regular cardinal $\lambda < \kappa$.

Theorem 9. *For a regular cardinal κ the following are equivalent.*

- For any Π_1^{1f} sentence $\forall F \psi(F, G)$, if $\models_{V_\kappa} \forall F \psi(F, G)$ then for some regular cardinal $\lambda < \kappa$, $G \cap V_\lambda$ is total and $\models_{V_\lambda} \forall F \psi(F, G \cap V_\lambda)$.*
- For any Π_1^{1f} sentence $\forall F \psi(F, G)$ where $G \cap V_\lambda$ is total for all regular cardinals $\lambda < \kappa$, if $\models_{V_\kappa} \forall F \psi(F, G)$ then for some regular cardinal $\lambda < \kappa$, $\models_{V_\lambda} \forall F \psi(F, G \cap V_\lambda)$.*
- κ is weakly compact.*

Proof. $a \Rightarrow b$ is immediate. Suppose b holds. Suppose ϕ is a Π_1^{1s} formula $\forall X \psi(X, Y)$. Let ϕ' be $\forall F \psi'(F, \chi_Y)$ where ψ' is the translation of ψ obtained using lemma 3. That $b \Rightarrow c$ follows, noting that $\chi_Y \cap V_\lambda$ is total.

Suppose κ is weakly compact. Given $\phi = \forall F \psi(F, G)$, let ϕ' be $\text{Tot}(\gamma_G) \wedge \forall X (\text{Func}(X) \Rightarrow \psi')$ where ψ' is the translation of ψ obtained using lemma 1,

Func is as in lemma 2, and $\text{Tot}(X)$ is the first order predicate “ X is total”. Then $\models_{V_\kappa} \phi'$, so $\models_{V_\lambda} \phi'$ for some λ , so $G \cap V_\lambda$ is total and $\models_{V_\lambda} \phi$. Thus, $c \Rightarrow a$. \square

Say that a regular cardinal κ has the downset property iff, whenever $D \subseteq \mathcal{N}$ is an unbranched downset, there is a regular cardinal $\lambda < \kappa$ such that $D \cap V_\lambda$ is unbranched.

Theorem 10. *If a regular cardinal κ has the downset property then κ is weakly compact.*

Proof. Suppose ϕ is a Π_1^{1f} formula, which may be assumed to be in normal form $\forall \vec{F} \exists \vec{x} \psi$ where ψ is Δ_1^{1f} , has no first order parameters, and for a second order parameter G and a regular cardinal κ $G \cap V_\lambda$ is total. Suppose ϕ is true in V_κ . Then the downset $D_{@G}$ of theorem 8 is unbranched. By hypothesis $D_{@G} \cap V_\lambda$ is unbranched for some regular cardinal $\lambda < \kappa$. By theorem 8 ϕ is true in V_λ . \square

Theorem 11. *If κ is a weakly compact cardinal then κ has the downset property.*

Proof. There is a Π_1^{1f} sentence in the parameter D which is true in V_λ for a regular cardinal λ iff D is an unbranched downset. \square

6. Concluding Remarks

It is a question of considerable interest, whether the existence of weakly compact cardinals can be justified by postulating sufficiently long stationary set chains (see[2]). Although the results given here do not shed much light on the problem, they do indicate that methods from descriptive set theory can be adopted to some extent. This suggests that further research in this area might be of interest.

References

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