

NEW EXTENDED BASED ON GENERALIZATION OF TEMBHURNE-SATHE ALGORITHM

Anton Iliev^{1,2}, Nikolay Kyurkchiev^{1,2},
Asen Rahnev¹ and Todorka Terzieva¹

¹Faculty of Mathematics and Informatics
University of Plovdiv Paisii Hilendarski
24, Tzar Asen Str., 4000 Plovdiv, BULGARIA

²Institute of Mathematics and Informatics
Bulgarian Academy of Sciences
Acad. G. Bonchev Str., Bl. 8, 1113 Sofia, BULGARIA

ABSTRACT: In this research we present new extended algorithm which is generalization of Tembhurne-Sathe algorithm [3] as well as our previous enhanced versions of Tembhurne-Sathe algorithm [11] and [29]. Also we give new faster organizations of classical Tembhurne-Sathe algorithm [3].

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1. INTRODUCTION

Let a and b are arbitrary natural numbers. We will construct new algorithm for finding integer numbers x and y such that $x * a + y * b = \text{Greatest Common Divisor (gcd)}$ of a and b . Euclidean algorithms are part of every contemporary book in algorithms,

see [1]–[9] and [30]–[47]. We explain how such algorithms (classical and new) can be successfully optimized [10]–[29].

For testing purposes we will use the following computer: processor – Intel(R) Core(TM) i7-6700HQ CPU 2.60GHz, 2592 Mhz, 4 Core(s), 8 Logical Processor(s), RAM 16 GB, Microsoft Windows 10 Enterprise x64, Microsoft Visual C# 2017 x64.

2. MAIN RESULTS

We present new faster iterative version of Tembhurne-Sathe algorithm:

Algorithm 1.

```

int g = 0;
if ((a & 1) == 0 && (b & 1) == 0)
do { a >>= 1; b >>= 1; g++; }
while ((a & 1) == 0 && (b & 1) == 0);
do
{
if (a > b)
{
a %= b; b -= a;
if ((b & 1) == 0) do { b >>= 1;
if (b == 1) { gcd = 1 << g; break; } }
while ((b & 1) == 0);
if ((a & 1) == 0) do {
if (a == 0) { gcd = b << g; break; } a >>= 1; }
while ((a & 1) == 0);
if (a == 0) break;
}
else
{
b %= a; a -= b;
if ((a & 1) == 0) do { a >>= 1;
if (a == 1) { gcd = 1 << g; break; } }
while ((a & 1) == 0);
if ((b & 1) == 0) do {

```

```

if (b == 0) { gcd = a << g; break; } b >>= 1; }
while ((b & 1) == 0);
if (b == 0) break;
}
} while (true);

```

as well as its recursive version as

Algorithm 2.

```

static long Euclid(long a, long b)
{
if ((a & 1) == 0 && (b & 1) == 0)
return Euclid(a >> 1, b >> 1) << 1;
if (a > b)
{ a %= b; b -= a;
if ((b & 1) == 0) { b >>= 1; if (b == 1) return 1; }
if ((a & 1) == 0) { if (a == 0) return b; a >>= 1; } }
else { b %= a; a -= b;
if ((a & 1) == 0) { a >>= 1; if (a == 1) return 1; }
if ((b & 1) == 0) { if (b == 0) return a; b >>= 1; } }
return Euclid(a, b);
}

```

The recursive function can be called by:

```
gcd = Euclid(a, b);
```

New iterative extended algorithm is:

Algorithm 3.

```

x1 = 1; x2 = 0; y1 = 0; y2 = 1;
int g = 0;
if ((a & 1) == 0 && (b & 1) == 0)

```

```

do { a >>= 1; b >>= 1; g++; }
while ((a & 1) == 0 && (b & 1) == 0);
u = a; v = b;
do
if (u > v)
{
q = u / v; u %= v;
x1 -= q * y1; x2 -= q * y2;
if (u < 1) { x = y1; y = y2; gcd = v << g; break; }
v -= u; y1 -= x1; y2 -= x2;
if (u == v) { x = x1; y = x2; gcd = u << g; break; }
if ((v & 1) == 0) do { v >>= 1;
if ((y1 & 1) == 0 && (y2 & 1) == 0) { y1 >>= 1; y2 >>= 1; }
else { y1 = (y1 + b) >> 1; y2 = (y2 - a) >> 1; }
if (v == 1) { x = x1; y = x2; gcd = 1 << g; break; }
} while ((v & 1) == 0);
if ((u & 1) == 0) do {
if (u == 0) { x = y1; y = y2; gcd = v << g; break; }
u >>= 1;
if ((x1 & 1) == 0 && (x2 & 1) == 0) { x1 >>= 1; x2 >>= 1; }
else { x1 = (x1 + b) >> 1; x2 = (x2 - a) >> 1; }
} while ((u & 1) == 0);
}
else
{
q = v / u; v %= u;
y1 -= q * x1; y2 -= q * x2;
if (v < 1) { x = x1; y = x2; gcd = u << g; break; }
u -= v; x1 -= y1; x2 -= y2;
if (u == v) { x = y1; y = y2; gcd = v << g; break; }
if ((u & 1) == 0) do
{ u >>= 1;
if ((x1 & 1) == 0 && (x2 & 1) == 0) { x1 >>= 1; x2 >>= 1; }
else { x1 = (x1 + b) >> 1; x2 = (x2 - a) >> 1; }
if (u == 1) { x = y1; y = y2; gcd = 1 << g; break; }
} while ((u & 1) == 0);
}

```

```

if ((v & 1) == 0) do {
if (v == 0) { x = x1; y = x2; gcd = u << g; break; }
v >>= 1;
if ((y1 & 1) == 0 && (y2 & 1) == 0) { y1 >>= 1; y2 >>= 1; }
else { y1 = (y1 + b) >> 1; y2 = (y2 - a) >> 1; }
} while ((v & 1) == 0);
}
while (true);

```

and its recursive analogue:

Algorithm 4.

```

static long Euclid(long u, long v, long a, long b,
ref long x, ref long y, long x1, long x2, long y1, long y2, int g)
{
long q;
if (u > v)
{
q = u / v; u %= v;
x1 -= q * y1; x2 -= q * y2;
if (u < 1) { x = y1; y = y2; return v << g; }
v -= u; y1 -= x1; y2 -= x2;
if (u == v) { x = x1; y = x2; return u << g; }
if ((v & 1) == 0)
{
if ((y1 & 1) == 0 && (y2 & 1) == 0) { y1 >>= 1; y2 >>= 1; }
else { y1 = (y1 + b) >> 1; y2 = (y2 - a) >> 1; }
if (v == 1) { x = x1; y = x2; return 1 << g; }
return Euclid(u, v >> 1, a, b, ref x, ref y, x1, x2, y1, y2, g);
}
if ((u & 1) == 0)
{
if (u == 0) { x = y1; y = y2; return v << g; }
if ((x1 & 1) == 0 && (x2 & 1) == 0) { x1 >>= 1; x2 >>= 1; }
else { x1 = (x1 + b) >> 1; x2 = (x2 - a) >> 1; }
}
}

```

```

return Euclid(u >> 1, v, a, b, ref x, ref y, x1, x2, y1, y2, g);
}
}
else
{
q = v / u; v %= u;
y1 -= q * x1; y2 -= q * x2;
if (v < 1) { x = x1; y = x2; return u << g; }
u -= v; x1 -= y1; x2 -= y2;
if (u == v) { x = y1; y = y2; return v << g; }
if ((u & 1) == 0)
{
if ((x1 & 1) == 0 && (x2 & 1) == 0) { x1 >>= 1; x2 >>= 1; }
else { x1 = (x1 + b) >> 1; x2 = (x2 - a) >> 1; }
if (u == 1) { x = y1; y = y2; return 1 << g; }
return Euclid(u >> 1, v, a, b, ref x, ref y, x1, x2, y1, y2, g);
}
}
if ((v & 1) == 0)
{
if (v == 0) { x = x1; y = x2; return u << g; }
if ((y1 & 1) == 0 && (y2 & 1) == 0) { y1 >>= 1; y2 >>= 1; }
else { y1 = (y1 + b) >> 1; y2 = (y2 - a) >> 1; }
return Euclid(u, v >> 1, a, b, ref x, ref y, x1, x2, y1, y2, g);
}
}
return Euclid(u, v, a, b, ref x, ref y, x1, x2, y1, y2, g);
}

```

and its calling

```

x1 = 1; x2 = 0; y1 = 0; y2 = 1;
int g = 0;
if ((a & 1) == 0 && (b & 1) == 0)
do { a >>= 1; b >>= 1; g++; }
while ((a & 1) == 0 && (b & 1) == 0);
u = a; v = b;

```

```
gcd = Euclid(u, v, a, b, ref x, ref y, x1, x2, y1, y2, g);
```

Numerical Example.

For testing purposes of Algorithms 1, 2, 3 and 4 we will use the following main function:

```
long a, b, gcd, d1 = 0, x = 0, y = 0;
long x1, x2, y1, y2, q, u, v;
for (int i = 1; i < 100000001; i++) { a = i; b = 200000002 - i;
//here are placed the source code of algorithms 1 and 3
//as well as calling of recursive algorithms 2 and 4
d1 += gcd;
}
Console.WriteLine(d1);
```

CPU time results are:

CPU time of Algorithm 1 is: **30.001 seconds**.

CPU time of Algorithm 2 is: **40.007 seconds**.

CPU time of Algorithm 3 is: **46.274 seconds**.

CPU time of Algorithm 4 is: **64.157 seconds**.

If compare the same numerical example with extended Harris iterative algorithm [28] which gives time **48.056 seconds** and extended Harris recursive algorithm [28] which gives time **86.152 seconds** we can conclude that new algorithms 3 and 4 are faster. The difference in time for optimized Tembhurne-Sathe algorithms 1, 2 and classical Tembhurne-Sathe iterative and recursive algorithms [3] which consume **40.455 seconds** and **95.786 seconds** is much bigger in benefit of new algorithms.

3. Conclusion

We obtain new extended algorithm. Numerical experiments give us confirmation of its superior computational speed.

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