

EXISTENCE AND UNIQUENESS OF SOLUTIONS FOR
A QUASILINEAR ELLIPTIC EQUATION
INVOLVING p -LAPLACIAN

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Abstract: In the present paper, using direct variational approach, the existence and uniqueness of solutions for a quasilinear elliptic equation involving the p -Laplacian is obtained.

AMS Subject Classification: 35J05, 35J35, 35J62, 35J92

Key Words: p -Laplacian, variational approach, quasilinear elliptic equation, Sobolev spaces

1. Introduction

We study the existence and uniqueness of solutions to the following Dirichlet boundary problem

$$\begin{cases} -\Delta_p u = f(u) + h(x) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad ((P))$$

where Ω is a bounded smooth domain of \mathbb{R}^N , $N \geq 3$, $2 \leq p < N$, $f : \mathbb{R} \rightarrow \mathbb{R}$ is

Received: April 23, 2012

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a continuous function and $h \in L^{p/p-1}(\Omega)$.

The importance of problem **(P)** arises from the existence of the p -Laplacian or the p -Laplace operator $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2} \nabla u)$. Obviously, when $p = 2$, $\Delta_2 = \Delta$ is the usual Laplace operator. However, in case $p \neq 2$ the situation is very crucial, as for example, one encounters the lack of the Hilbert structure of the space $W_0^{1,p}(\Omega)$ when passing from $p = 2$ to $p \neq 2$.

It is well known that problems involving the p -Laplacian appear in many contexts. Some of these problems come from different areas of applied mathematics and physics. For example, they may be found in the study of non-Newtonian fluids, nonlinear elasticity, and reaction diffusions. For discussions about problems modelled by these boundary value problems, see, for example, [4]. One of the most widely used results for solving problem **(P)** is the mountain pass theorem. In order to apply this theorem, it is necessary that the Euler-Lagrange functional associated to the problem has the Palais-Smale property. One way to ensure this is to assume that f satisfies some Ambrosetti-Rabinowitz-type condition (see, e.g., [2, 5]). Another technique used for obtaining solutions of problem **(P)** is the blowup method due to Gidas and Spruck [6]. In order to use any of the techniques above, it is necessary that the nonlinearity f has subcritical growth. The object of this paper is to study problem **(P)** for nonlinearities f which do not necessarily satisfy the classical conditions, such as Ambrosetti-Rabinowitz condition, but are limited by functions that do satisfy some specific conditions.

$L^p(\Omega)$, for $1 \leq p < \infty$, is the Lebesgue space of measurable functions $u : \Omega \rightarrow \mathbb{R}$ such that $\int_{\Omega} |u|^p dx < +\infty$, while $L^\infty(\Omega)$ is the space of measurable functions such that $\operatorname{ess\,sup}_{x \in \Omega} |u(x)| < +\infty$. The norms that make $L^p(\Omega)$ Banach spaces are, respectively,

$$|u|_p = \left(\int_{\Omega} |u|^p dx \right)^{1/p} \quad \text{and} \quad |u|_\infty = \operatorname{ess\,sup} |u(x)|.$$

Let $W^{1,p}(\Omega)$ be the usual Sobolev space, i.e.,

$$W^{1,p}(\Omega) = \{u \in L^p(\Omega) : \nabla u \in L^p(\Omega)\}$$

which is endowed with norm

$$\|u\| = \left(\int_{\Omega} (|\nabla u|^p + |u|^p) dx \right)^{1/p}. \quad (1.1)$$

Then $W^{1,p}(\Omega)$ is a Banach space. $W_0^{1,p}(\Omega)$ is the closure of $C_0^\infty(\Omega)$ in $W^{1,p}(\Omega)$.

In $W_0^{1,p}(\Omega)$ we use the norm

$$\|u\|_{W_0^{1,p}(\Omega)} = \left(\int_{\Omega} |\nabla u|^p dx \right)^{1/p}. \tag{1.2}$$

Thanks to the Poincaré inequality, it is not difficult to see that (1.1) and (1.2) are equivalent. Therefore, in the sequel the norm in $W_0^{1,p}(\Omega)$ will be denoted by $\|\cdot\|$.

Let Ω be an open and bounded subset of \mathbb{R}^N , with $N \geq 3$. Then $W_0^{1,p}(\Omega)$ is embedded continuously in $L^q(\Omega)$, denoted by $W_0^{1,p}(\Omega) \hookrightarrow L^q(\Omega)$, for every $q \in [1, p^*]$, where $p^* = Np/N - p$. The embedding is compact if and only if $q \in [1, p^*)$ (see [1]).

$u \in W_0^{1,p}(\Omega)$ is a weak solution of **(P)** if any $\varphi \in W_0^{1,p}(\Omega)$,

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u \cdot \nabla \varphi dx = \int_{\Omega} f(u) \varphi dx + \int_{\Omega} h \varphi dx.$$

The energy functional corresponding to problem **(P)** is defined as $J : W_0^{1,p}(\Omega) \rightarrow \mathbb{R}$,

$$J(u) = \frac{1}{p} \int_{\Omega} |\nabla u|^p dx - \int_{\Omega} F(u) dx - \int_{\Omega} h u dx,$$

where $F(t) = \int_0^t f(s) ds$. It is well known that weak solutions of **(P)** correspond to critical points of the functional J .

The main result of the present paper is:

Theorem 1. *Assume that the following conditions hold:*

(f₀) $f : \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function, and assume that there exists $a, b > 0$ such that

$$|f(t)| \leq a + b |t|^{q-1}$$

for all $t \in \mathbb{R}$, where $1 < q < p^*$.

(f₁) $f(t)t \leq 0$ and $(f(t) - f(s))(t - s) \leq 0$ for all $t, s \in \mathbb{R}$.

Then problem **(P)** has exactly one solution.

Remark 1. As an example of function f satisfying the assumptions of Theorem 1, one can take $f(t) = -|t|^{r-2}t$ with $r \in (1, p^*)$.

2. Main Results

First, we give the following well-known Propositions which are necessary through the present paper (see, e.g., [3, 7, 9]).

Proposition 1. *Let X be a Banach space and let $I : X \rightarrow \mathbb{R}$ be a differentiable functional. Assume that for all $u, v \in X$,*

$$\langle I'(u) - I'(v), u - v \rangle \geq 0.$$

Then I is convex. If the strict inequality holds when $u \neq v$, then I is strictly convex.

Proposition 2. *Let functional $I : X \rightarrow \mathbb{R}$ be strictly convex and differentiable. Then I has at most one critical point in X .*

To obtain the result of Theorem 1, we need to show that the following two lemmas hold.

Lemma 1. (i) *The functional J is well-defined on $W_0^{1,p}(\Omega)$.*

(ii) *The functional J is of class $C^1(W_0^{1,p}(\Omega), \mathbb{R})$ and*

$$\langle J'(u), \varphi \rangle = \int_{\Omega} |\nabla u|^{p-2} \nabla u \cdot \nabla \varphi dx - \int_{\Omega} f(u) \varphi dx - \int_{\Omega} h \varphi dx,$$

for all $u, \varphi \in W_0^{1,p}(\Omega)$.

Proof. (i) From (f_0) , (f_1) , continuous embeddings and the Hölder inequality we have

$$\begin{aligned} J(u) &= \frac{1}{p} \int_{\Omega} |\nabla u|^p dx - \int_{\Omega} F(u) dx - \int_{\Omega} h u dx \\ &\leq \frac{1}{p} \|u\|^p + a \int_{\Omega} |u| dx + \frac{b}{q} \int_{\Omega} |u|^q dx - |h|_{\frac{p}{p-1}} \|u\|_p \\ &\leq \frac{1}{p} \|u\|^p + c_1 \|u\|^q + c_2 \|u\|, \end{aligned}$$

this implies that J is well-defined on $W_0^{1,p}(\Omega)$.

(ii) Let define

$$J(u) = \int_{\Omega} \left(\frac{1}{p} |\nabla u|^p - F(u) - hu \right) dx := \int_{\Omega} G(u) dx.$$

First, we will show that J is Gâteaux differentiable. Therefore we have to prove that for fixed $u, v \in W_0^{1,p}(\Omega)$,

$$\lim_{t \rightarrow 0} \int_{\Omega} \frac{G(u + tv) - G(u)}{t} = \int_{\Omega} \left(|\nabla u|^{p-2} \nabla u \cdot \nabla v - (f(u) + h)v \right) dx.$$

After elementary calculations, one can easily show that, for almost every $x \in \Omega$,

$$\begin{aligned} & \lim_{t \rightarrow 0} \frac{G(u(x) + tv(x)) - G(u(x))}{t} \\ &= |\nabla u(x)|^{p-2} \nabla u(x) \cdot \nabla v(x) - (f(u(x)) + h(x))v(x). \end{aligned}$$

Then, by the Lagrange theorem, there exists a real number θ such that $|\theta| \leq |t|$ and

$$\begin{aligned} & \left| \frac{G(u(x) + tv(x)) - G(u(x))}{t} \right| \\ &= \left| |\nabla(u(x) + \theta v(x))|^{p-2} \nabla(u(x) + \theta v(x)) \cdot \nabla v(x) \right. \\ & \quad \left. - (f(u(x) + \theta v(x)) + h(x))v(x) \right| \\ &\leq |\nabla(u(x) + \theta v(x))|^{p-1} |\nabla v(x)| + \left(a + b|u(x) + \theta v(x)|^{q-1} \right) |v(x)| + |h(x)v(x)| \\ &\leq |\nabla(u(x) + v(x))|^{p-1} |\nabla v(x)| + \left(a + b|u(x) + v(x)|^{q-1} \right) |v(x)| + |h(x)||v(x)| \\ &\leq |\nabla u(x)|^{p-1} |\nabla v(x)| + |\nabla v(x)|^p + |u(x)|^{q-1} |v(x)| \\ & \quad + |v(x)|^q + |v(x)| + |h(x)||v(x)|. \end{aligned} \tag{2.1}$$

By the Hölder inequality we get

$$\int_{\Omega} |\nabla u|^{p-1} |\nabla v| dx \leq \left| |\nabla u|^{p-1} \right|_{\frac{p}{p-1}} |\nabla v|_p,$$

and

$$\int_{\Omega} |u|^{q-1} |v| dx \leq \left| |u|^{q-1} \right|_{\frac{q}{q-1}} |v|_q, \quad \int_{\Omega} |h||v| dx \leq |h|_{\frac{p}{p-1}} |v|_p.$$

From the above inequalities, one concludes that the expression (2.1) is in $L^1(\Omega)$. Therefore by the dominated convergence theorem we have

$$\lim_{t \rightarrow 0} \int_{\Omega} \frac{G(u + tv) - G(u)}{t} = \int_{\Omega} \left(|\nabla u|^{p-2} \nabla u \cdot \nabla v - (f(u) + h)v \right) dx.$$

Since the right-hand side, as a function of v , is continuous linear functional on $W_0^{1,p}(\Omega)$, it is the Gâteaux differential of J .

Now, we will prove that $J' : W_0^{1,p}(\Omega) \rightarrow (W_0^{1,p}(\Omega))^*$ is continuous. Assume $u_k \rightarrow u$ in $W_0^{1,p}(\Omega)$. Up to a subsequence, we may assume that
 $u_k \rightarrow u$ in $L^p(\Omega)$ and in $L^q(\Omega)$ as $k \rightarrow \infty$;
 $u_k(x) \rightarrow u(x)$ a.e. in Ω as $k \rightarrow \infty$.
 Then, by the Hölder inequality we have

$$\begin{aligned} & | \langle J'(u_k) - J'(u), v \rangle | \\ & \leq \int_{\Omega} \left| \left(|\nabla u_k|^{p-2} \nabla u_k - |\nabla u|^{p-2} \nabla u \right) \cdot \nabla v + (f(u) - f(u_k))v \right| dx \\ & \leq \int_{\Omega} \left| |\nabla u_k|^{p-2} \nabla u_k - |\nabla u|^{p-2} \nabla u \right| |\nabla v| dx + \int_{\Omega} |f(u_k) - f(u)| |v| dx \\ & \leq \int_{\Omega} \left(|\nabla u_k|^{p-1} + |\nabla u|^{p-1} \right) |\nabla v| dx + \int_{\Omega} |f(u_k) - f(u)| |v| dx. \end{aligned}$$

Since $u_k \rightarrow u$ in $L^p(\Omega)$, it is obvious that $(|\nabla u_k|^{p-1} + |\nabla u|^{p-1}) |\nabla v| \in L^1(\Omega)$. Let's proceed for the second term. By the Hölder inequality we obtain

$$\int_{\Omega} |f(u_k) - f(u)| |v| dx \leq \left(\int_{\Omega} |f(u_k) - f(u)|^{q/q-1} dx \right)^{q-1/q} \left(\int_{\Omega} |v|^q dx \right)^{1/q}.$$

From (f_0) we have

$$|f(u_k) - f(u)|^{q/q-1} \leq c \left(1 + |u_k|^{q-1} + |u|^{q-1} \right)^{q/q-1}.$$

Since $u_k \rightarrow u$ in $L^q(\Omega)$, there exists $\varphi \in L^q(\Omega)$ such that $|u_k(x)| \leq \varphi(x)$ a.e. in Ω and for all $k \in \mathbb{N}$. Therefore

$$\begin{aligned} |f(u_k) - f(u)|^{q/q-1} & \leq c_1 \left(1 + |\varphi|^{q-1} + |u|^{q-1} \right)^{q/q-1} \\ & \leq c_2 (1 + |\varphi|^q + |u|^q) \in L^1(\Omega). \end{aligned}$$

On the other hand, taking into account that $u_k(x) \rightarrow u(x)$ a.e. in Ω as $k \rightarrow \infty$, we also get

$$\lim_{k \rightarrow \infty} \left| |\nabla u_k(x)|^{p-2} \nabla u_k(x) - |\nabla u(x)|^{p-2} \nabla u(x) - (f(u_k(x)) - f(u(x))) \right| = 0.$$

If we consider the above inequalities and apply the dominated convergence theorem, we obtain

$$\lim_{k \rightarrow \infty} \int_{\Omega} \left| |\nabla u_k|^{p-2} \nabla u_k - |\nabla u|^{p-2} \nabla u - (f(u_k) - f(u)) \right| = 0,$$

which implies

$$\limsup_{k \rightarrow \infty} \|J'(u_k) - J'(u)\| = 0.$$

So we deduce that Gâteaux differential of J is continuous, i.e. J is of class $C^1(W_0^{1,p}(\Omega), \mathbb{R})$. □

Lemma 2. (i) *The functional J is coercive.*

(ii) *The functional J is strictly convex.*

Proof. (i) From (f_1) , it is clear that $F(t) \leq 0$ for all $t \in \mathbb{R}$, and hence we have

$$\begin{aligned} J(u) &= \frac{1}{p} \int_{\Omega} |\nabla u|^p dx - \int_{\Omega} F(u) dx - \int_{\Omega} h u dx \\ &\geq \frac{1}{p} \|u\|^p - c \|u\|, \end{aligned}$$

this implies that J is coercive.

(ii) For all $u, v \in W_0^{1,p}(\Omega)$ for $u \neq v$, from (f_1) we have

$$\begin{aligned} &\langle I'(u) - I'(v), u - v \rangle \\ &= \int_{\Omega} (|\nabla u|^{p-2} \nabla u - |\nabla v|^{p-2} \nabla v) \cdot (\nabla u - \nabla v) dx \\ &\quad - \int_{\Omega} (f(u) - f(v))(u - v) dx \\ &\geq \int_{\Omega} (|\nabla u|^{p-2} \nabla u - |\nabla v|^{p-2} \nabla v) \cdot (\nabla u - \nabla v) dx. \end{aligned}$$

Next, we apply the following well-known inequality (see [8]), for any $\xi, \eta \in \mathbb{R}^N$

$$\left(|\xi|^{r-2} \xi - |\eta|^{r-2} \eta \right) \cdot (\xi - \eta) \geq 2^{-r} |\xi - \eta|^r, \quad r \geq 2.$$

Therefore, one easily concludes that

$$\langle I'(u) - I'(v), u - v \rangle \geq 2^{-p} \int_{\Omega} |\nabla(u - v)|^p dx = 2^{-p} \|u - v\|^p > 0.$$

This shows that J is strictly convex. □

Proof of Theorem 1. As the functional J is continuous, convex and coercive, it has a global minimum point, which is a critical point. Furthermore, since J is strictly convex and differentiable, by Proposition 4, J must have only one critical point. □

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